

## SERVO Earthquake Science Grid

SERVOGrid (<http://www.servogrid.org>) is a project led by JPL and involving Brown University, Indiana University, UC Davis and Irvine and the University of Southern California. It is a prototype for a future international project iSERVO – the International Solid Earth Research Virtual Observatory – linking Australia, China, Japan and the USA.

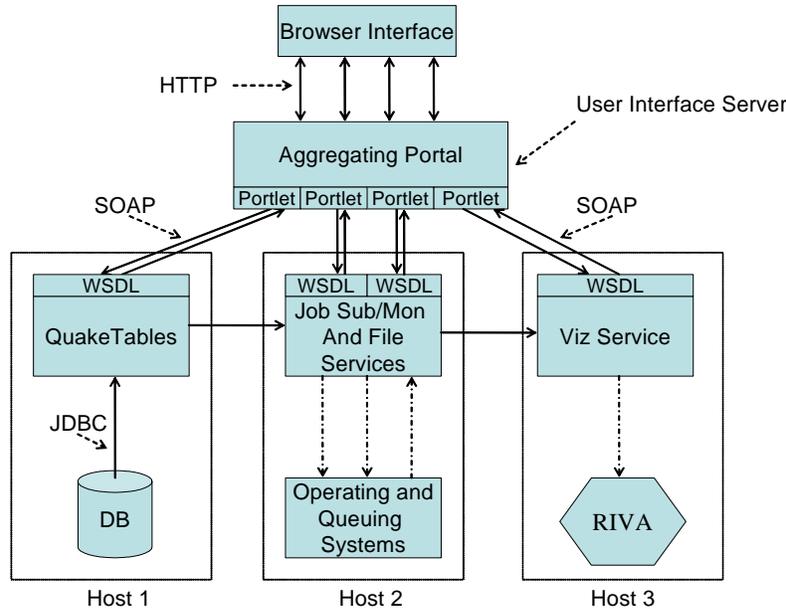


Figure 1 SERVO Grid is built using component-based portals and Web Services. This shows a job submission and management service linked to data service (Fault database Quaketables) and a visualization service. The user interfaces to this set of Grid Services is provided by an aggregation portal whose portlet architecture supports a component model of user interfaces illustrated in fig. 2.

The architecture of SERVOGrid is shown in fig. 1 and it is built in terms of the Web Service Grid architecture described in [http://www.nesc.ac.uk/technical\\_papers/UKeS-2004-05.pdf](http://www.nesc.ac.uk/technical_papers/UKeS-2004-05.pdf). SERVOGrid offers services that support simulation codes wrapped as services, job submission and monitoring, file management, workflow (or the composition of multiple services), databases and GML (Geography Markup Language) based observations. Initial application codes wrapped as services include mesh generation, data-mining and a variety of simulation codes including Virtual California from UC Davis, GEOFEST from JPL and Finley from the University of Queensland in Australia. SERVOGrid is architected as a Grid of Grids with component Grids supporting data, job execution, visualization and Geographical Information services (GIS). A data transport layer supports fault tolerant high performance streaming compatible with Web Service standards such as SOAP and reliable messaging. The OGC (Open Geospatial Consortium) Web Feature and Map services have been prototyped and will be extended to a full GIS Grid. An ontology layer allows intelligent linkage of services with a Semantic Grid architecture.

