

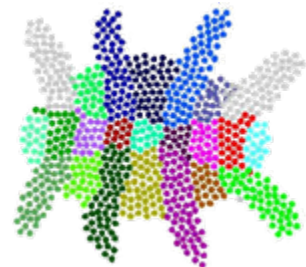
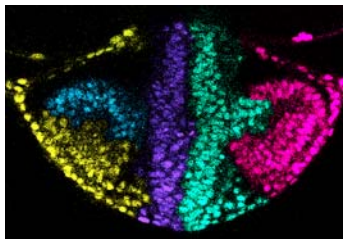
Heterogeneous collective motion or *moving* pattern formation?

The two sides of embryogenesis combined by
multi-agent modeling into a

self-made
puzzle

René Doursat

<http://www.iscpif.fr/~doursat>



Systems that are self-organized and architected



free self-organization

the scientific challenge of complex systems: how can they integrate a true *architecture*?



Peugeot Picasso

the engineering challenge of complicated systems: how can they integrate *self-organization*?

deliberate design

components evolve

Peugeot Picasso



decompose the system

self-organized architecture / architected self-organization

Toward programmed self-organization

➤ Self-organized (complex) systems

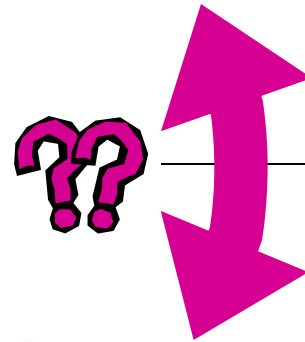
- ✓ a myriad of self-positioning, self-assembling agents
- ✓ collective order is not imposed from outside (only influenced)
- ✓ comes from purely *local* information & interaction around each agent
- ✓ no agent possesses the global map or goal of the system
- ✓ but every agent may contain all the *rules* that contribute to it



➤ Structured systems

- ✓ true *architecture*: non-trivial, complicated morphology
 - *hierarchical*, multi-scale: regions, parts, details, agents
 - *modular*: reuse, quasi-repetition
 - *heterogeneous*: differentiation & divergence in the repetition
- ✓ *random* at the microscopic level, *but reproducible* (quasi deterministic) at the mesoscopic and macroscopic levels

eradicate any illusion of ID by explaining the developmental mechanisms of spontaneous architecture formation (not just evolutionary)



Quick preview of multi-agent embryogenesis

➤ An abstract (computational), top-down approach



- ✓ development as a fundamentally *spatiotemporal* phenomenon
- ✓ JAG: "*start generically*, treat cells as black boxes, add details gradually"
- ✓ highlighting the *broad principles* necessary to integrate and make sense of the data; proposing a *computational* model of these principles

➤ And the broad principles are...



1. *biomechanics* → collective motion → "sculpture" of the embryo
 2. *gene regulation* → gene expression patterns → "painting" of the embryo
- + *coupling* between *shapes* and *colors*

➤ Multi-agent models



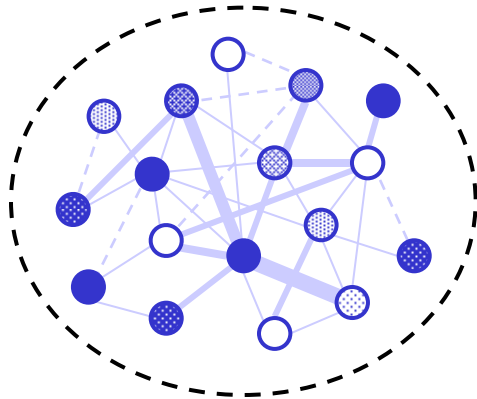
- ✓ best positioned to integrate both
- ✓ account for heterogeneity, modularity, hierarchy
- ✓ each agent carries a combined set of *biomechanical* and *regulatory* rules

The self-made puzzle of embryogenesis

1. Self-organized and structured systems
2. A two-side challenge: heterogeneous motion / moving patterns
3. A multi-agent model of embryogenesis
4. Evolutionary development (evo-devo)

Self-organized and structured systems

➤ Natural and human-made complex systems everywhere



- large number of elementary agents interacting **locally**
- simple individual behaviors creating a complex **emergent** collective behavior
- *decentralized dynamics: no master blueprint or grand architect*

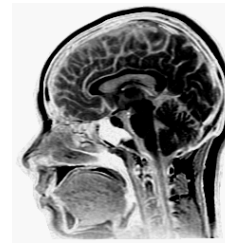
✓ **physical**, **biological**, **technical**, **social** systems (natural or artificial)



pattern formation
○ = matter



biological development
○ = cell

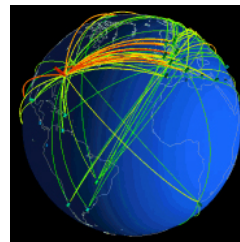


the brain & cognition
○ = neuron

insect colonies
○ = ant



Internet & Web
○ = host/page




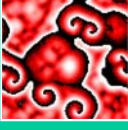




social networks
○ = person



"Statistical" vs. "morphological" complex systems

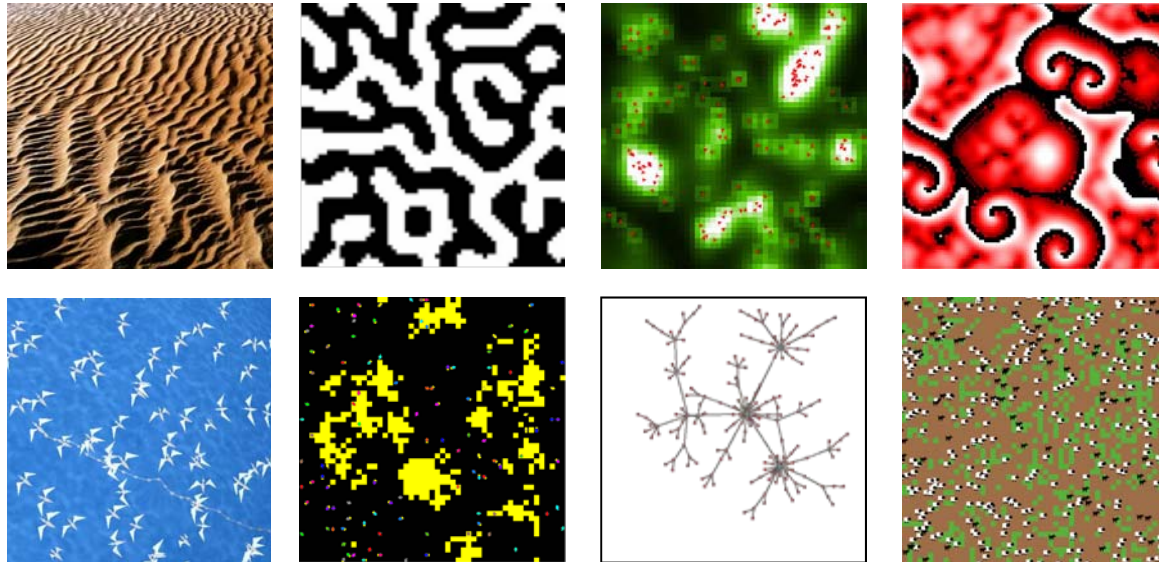
➤ A brief taxonomy of systems

Category	<i>Agents / Parts</i>	<i>Local Rules</i>	<i>Emergent Behavior</i>	<i>A "Complex System"?</i>
 2-body problem	<i>few</i>	<i>simple</i>	<i>simple</i>	<i>NO</i>
 3-body problem, low-D chaos	<i>few</i>	<i>simple</i>	<i>complex</i>	<i>NO - too small</i>
 crystal, gas	<i>many</i>	<i>simple</i>	<i>simple</i>	<i>NO - few params suffice to describe it</i>
 patterns, swarms, complex networks	<i>many</i>	<i>simple</i>	<i>"complex"</i>	<i>YES - but mostly random and uniform</i>
 embryogenesis	<i>many</i>	<i>sophisticated</i>	<i>complex</i>	<i>YES - reproducible and heterogeneous</i>
 machines, crowds with leaders	<i>many</i>	<i>sophisticated</i>	<i>"simple"</i>	<i>COMPLICATED - not self-organized</i>

Statistical (self-similar) systems

➤ Many agents, simple rules, “complex” emergent behavior

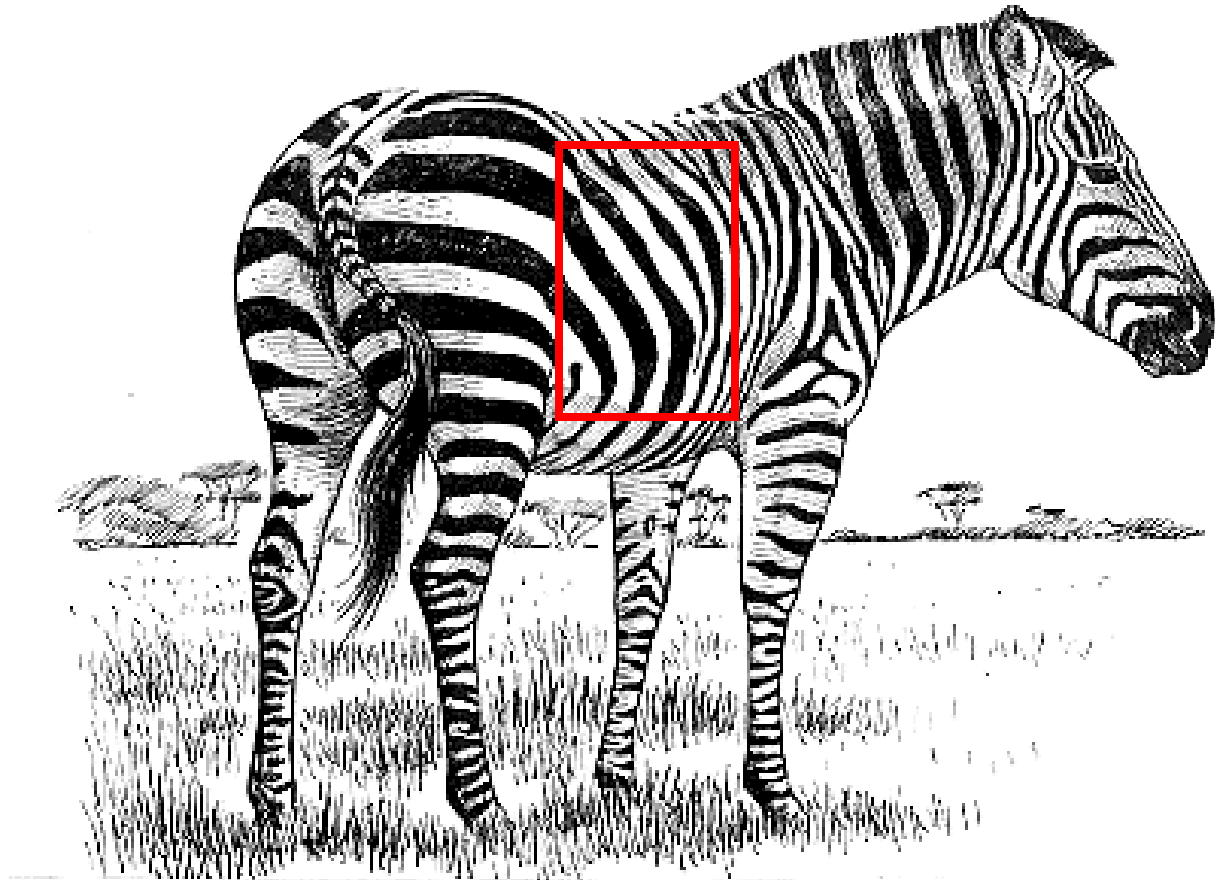
→ the “clichés” of complex systems: diversity of pattern formation (spots, stripes), swarms (clusters, flocks), complex networks, etc.



- ✓ yet, often like “textures”: repetitive, statistically *uniform*, information-poor
- ✓ spontaneous order arising from amplification of *random* fluctuations
- ✓ *unpredictable* number and position of mesoscopic entities (spots, groups)

Morphological (self-dissimilar) systems

compositional systems: pattern formation \neq morphogenesis



"I have the stripes, but where is the zebra?" OR
"The stripes are easy, it's the horse part that troubles me"
 —attributed to A. Turing, after his 1952 paper on morphogenesis

Morphological (self-dissimilar) systems

➤ Many agents, sophisticated rules, complex emergence

→ *natural ex: organisms (cells)*



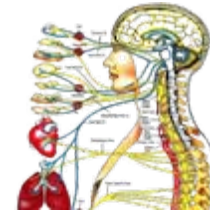
plants



vertebrates



arthropods



humans

- ✓ mesoscopic organs and limbs have intricate, *nonrandom* morphologies
- ✓ development is highly *reproducible* in number and position of body parts
- ✓ *heterogeneous* elements arise under information-rich genetic control

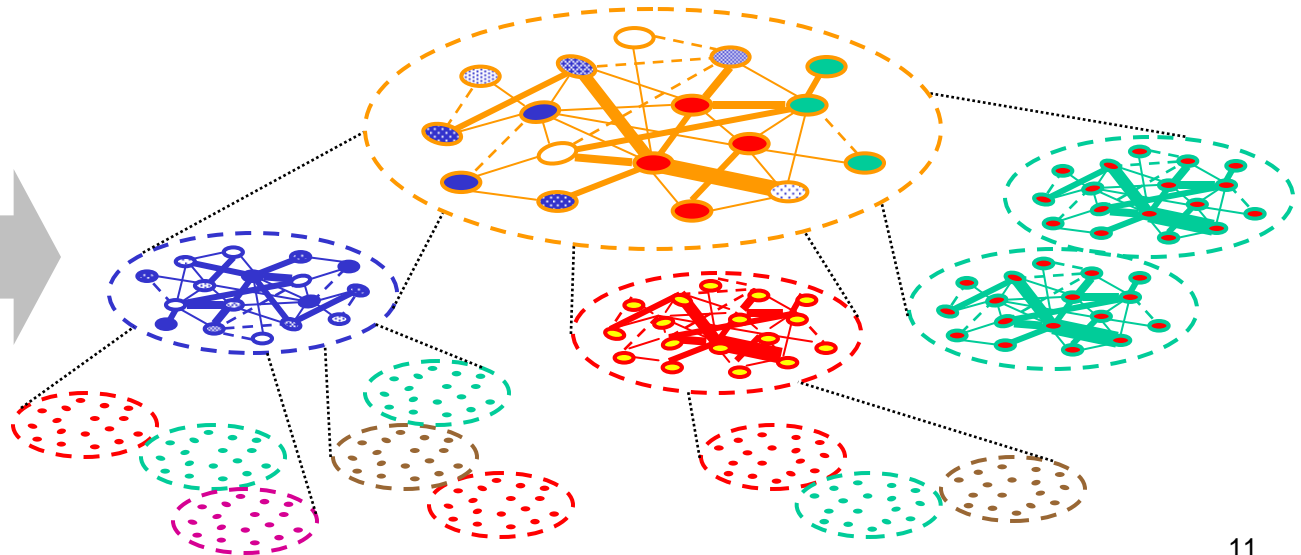
➤ Biological organisms are self-organized and structured

- ✓ because the pieces of the puzzle (agent rules) are more “sophisticated” (than inert matter): depend on agent’s *type* and/or *position* in the system
- ✓ the outcome (development) is truly complex but, paradoxically, can also be more *controllable* and *programmable*

Beyond statistics: heterogeneity, modularity, reproducibility

➤ Complex systems can be much more than a "soup"

- ✓ "complex" doesn't necessarily imply "homogeneous"...
→ *heterogeneous agents and diverse patterns, via positions*
- ✓ "complex" doesn't necessarily imply "flat" (or "scale-free")...
→ *modular, hierarchical, detailed architecture (at specific scales)*
- ✓ "complex" doesn't necessarily imply "random"...
→ *reproducible patterns relying on programmable agents*

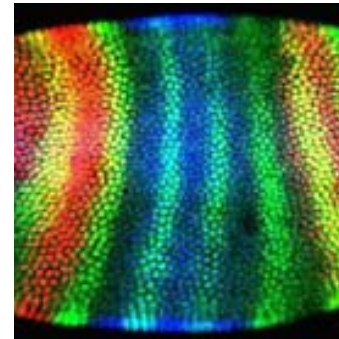


Statistical vs. morphological systems

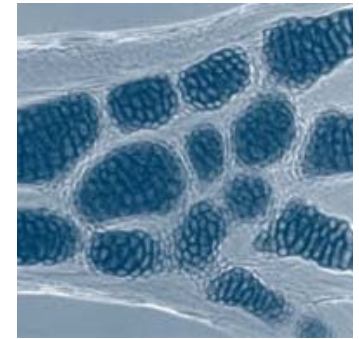
- Physical pattern formation is “free” –
- Biological (multicellular) pattern formation is “guided”



reaction-diffusion
with NetLogo



fruit fly embryo
Sean Carroll, U of Wisconsin



larval axolotl limb
condensations
Gerd B. Müller

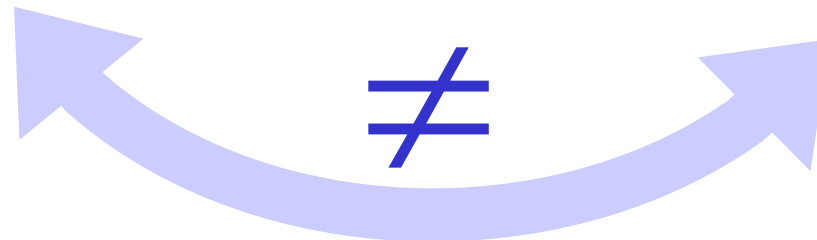


Fig. 8.2.

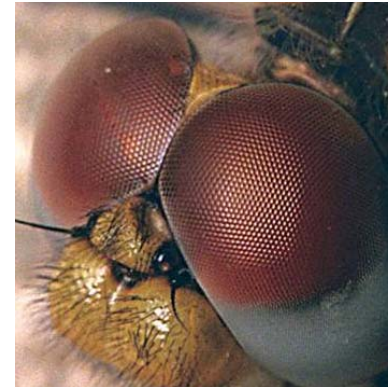
Statistical vs. morphological systems

- Multicellular forms = a bit of “free” + a lot of “guided”
 - ✓ domains of free patterning embedded in a guided morphology

unlike *Drosophila*'s stripes, these pattern primitives are *not* regulated by different sets of genes depending on their position



spots, stripes in skin
angelfish, www.sheddaquarium.org



ommatidia in compound eye
dragonfly, www.phy.duke.edu/~hsg/54

- ✓ repeated copies of a guided form, distributed in free patterns

entire structures (flowers, segments) can become modules showing up in random positions and/or numbers



flowers in tree
cherry tree, www.phy.duke.edu/~fortney



segments in insect
centipede, images.encyclopedia.msn.com

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Embryogenesis couples **assembly** and **patterning**

➤ Sculpture → forms

Ádám Szabó, *The chicken or the egg* (2005)
<http://www.szaboadam.hu>



“shape from patterning”

- ✓ the **forms** are “sculpted” by the self-assembly of the elements, whose behavior is triggered by the **colors**

➤ Painting → colors



“patterns from shaping”

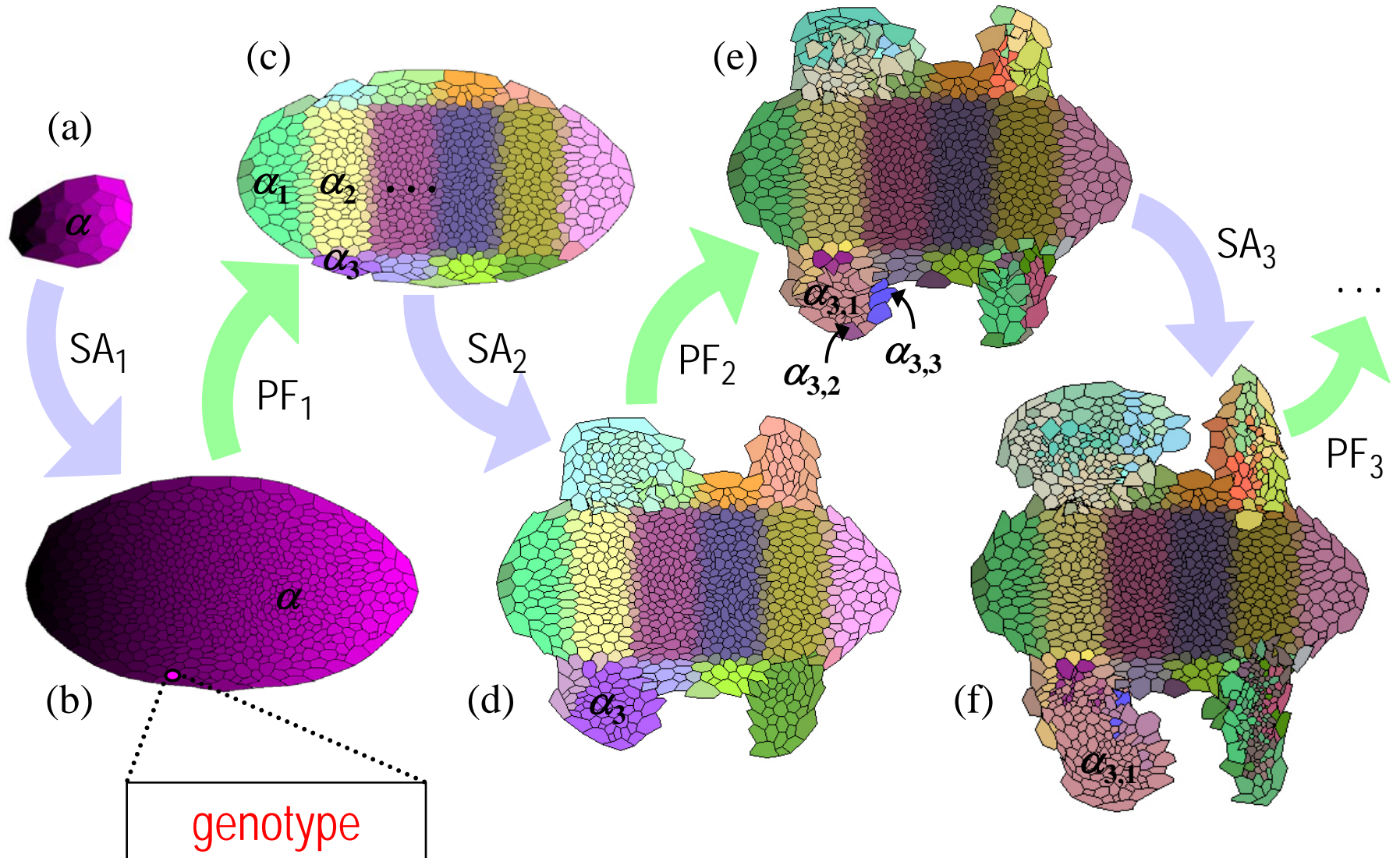
- ✓ new **color** regions appear (domains of genetic expression) triggered by **deformations**



Niki de Saint Phalle

Embryogenesis couples assembly and patterning

SA = self-assembly ("sculpture")
 PF = pattern formation ("painting")

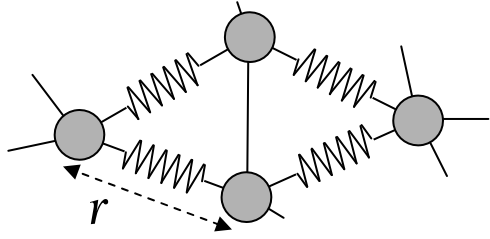
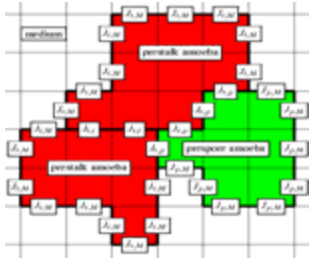
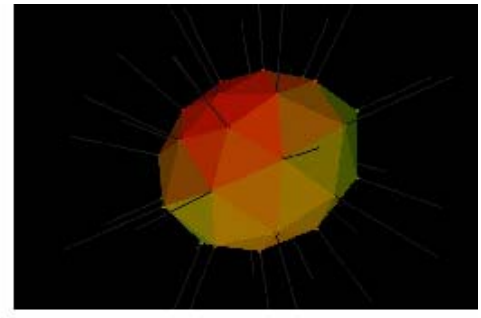
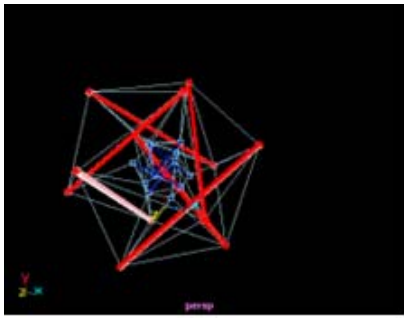


Embryogenesis couples mechanics and regulation

➤ Cellular mechanics

- ✓ adhesion
- ✓ deformation / reformation
- ✓ migration (motility)
- ✓ division / death

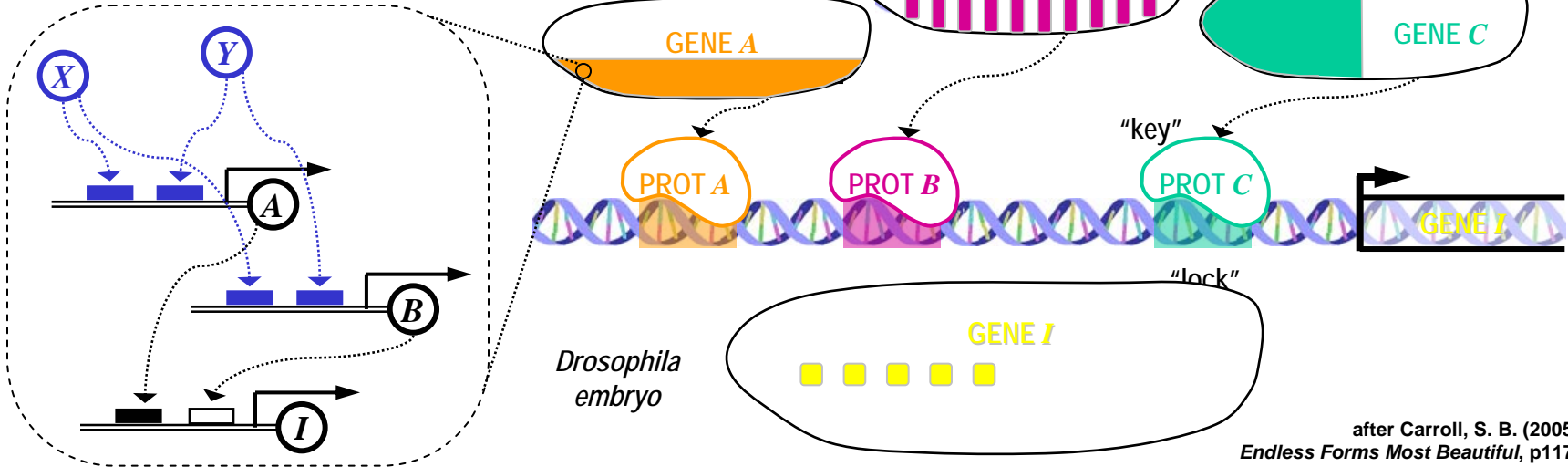
cellular Potts model (Graner, Glazier, Hogeweg) tensional integrity (Ingber)



(Dellie & Doursat)

(Doursat)

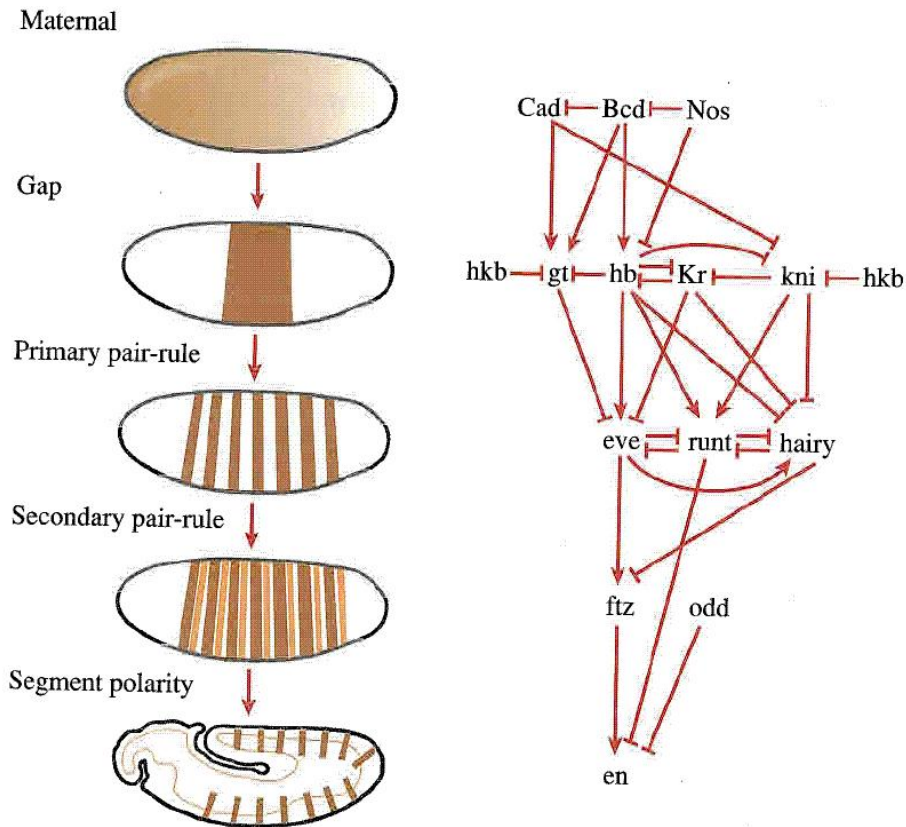
➤ Genetic regulation



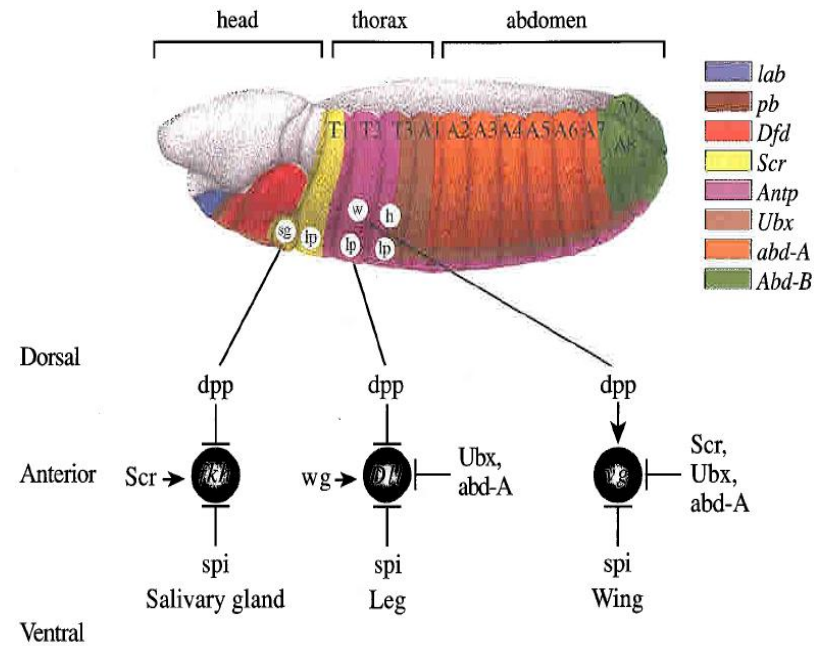
Gene regulatory pattern formation

➤ Segmentation & identity domains in *Drosophila*

- ✓ periodic A/P band patterns are controlled by a 5-tier gene regulatory hierarchy



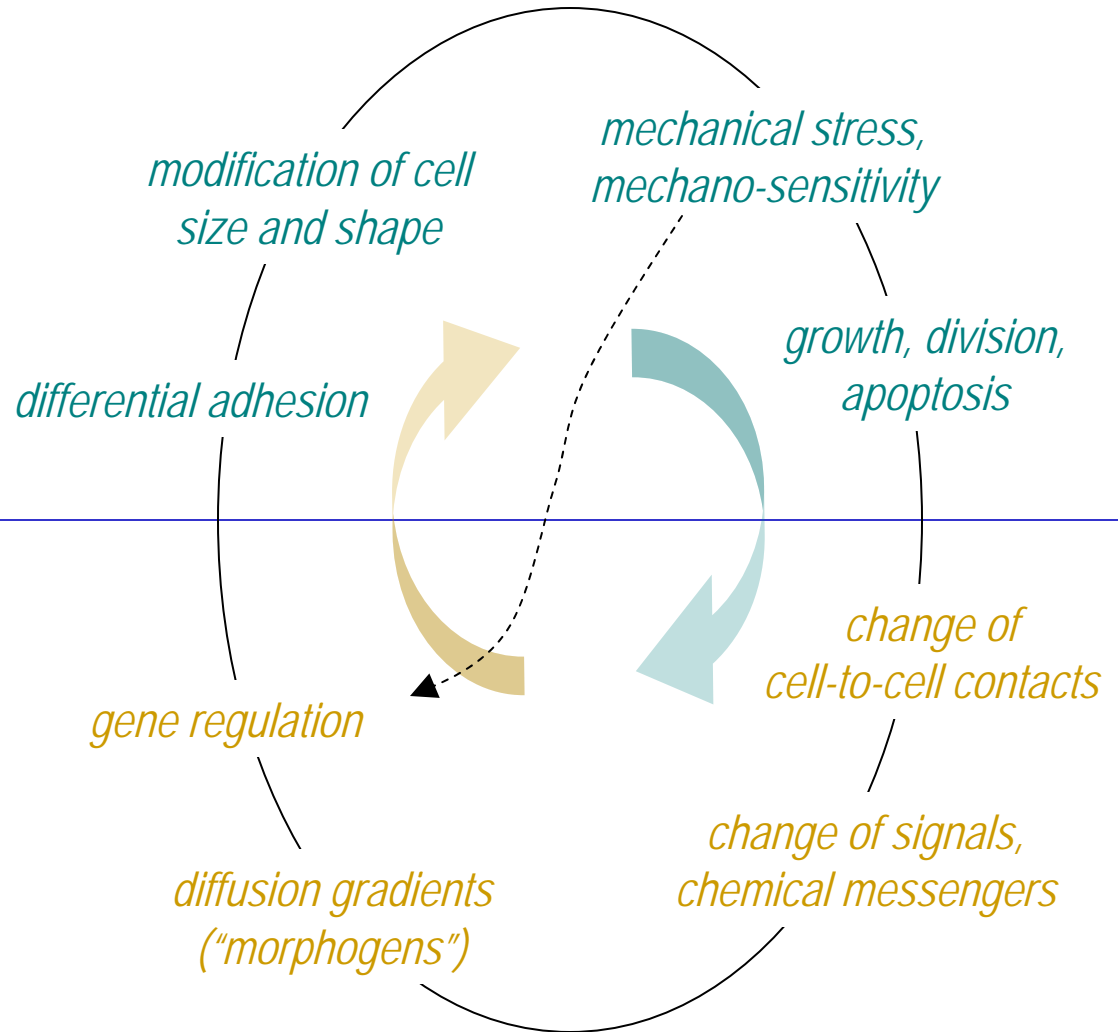
- ✓ intersection with other axes creates organ primordia and imaginal discs (identity domains of future legs, wings, antennae, etc.)



from Carroll, S. B., et al. (2001)
From DNA to Diversity, p63

Embryogenesis couples **mechanics** and **regulation**

➤ Cellular mechanics

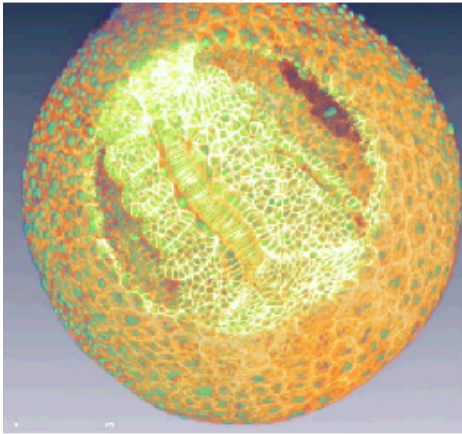


➤ Genetic regulation

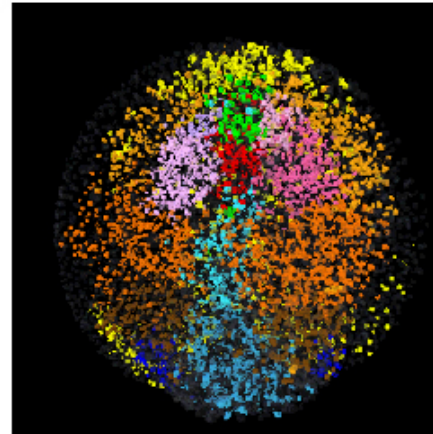
Embryogenesis couples motion and patterns

Nadine Peyri ras, Paul Bourguine, Thierry Savy,
Beno t Lombardot, Emmanuel Faure et al.
Embryomics & BioEmergences

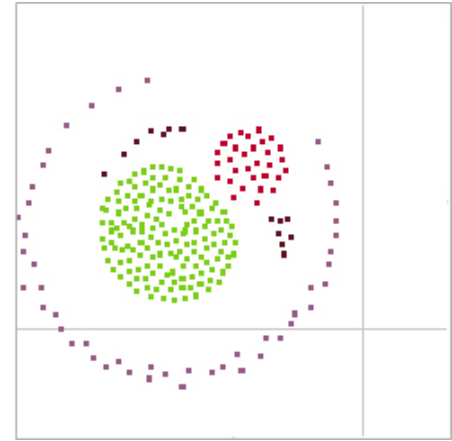
Collective motion regionalized into patterns



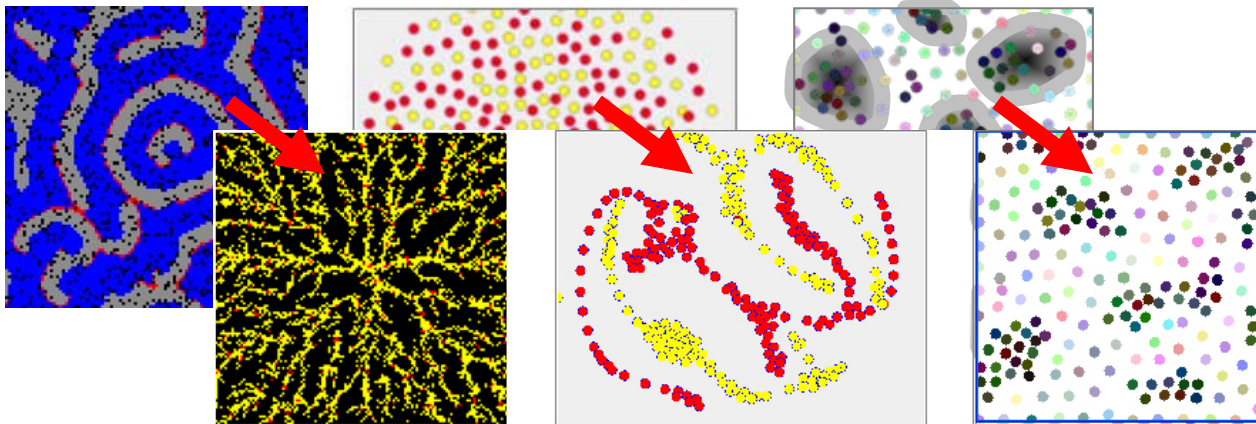
zebrafish



Hiroki Sayama (Swarm Chemistry)
<http://bingweb.binghamton.edu/~sayama/SwarmChemistry/>

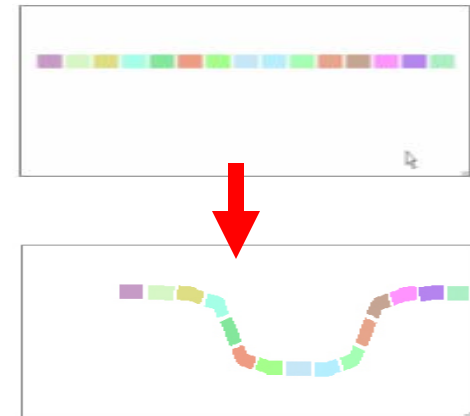


Pattern formation that triggers motion



<http://zool33.uni-graz.at/schmickl>

Doursat



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4. Evolutionary development (evo-devo)

Why multi-agent modeling?

➤ Equations and laws can be hard or impossible to find...

- ✓ *“The study of non-linear physics is like the study of non-elephant biology.”* —Stanislaw Ulam
 - the physical world is a fundamentally *non-linear* and *out-of-equilibrium* process
 - focusing on linear approximations and stable points is missing the big picture in most cases

- ✓ let's push this quip: *“The study of **non-analytical complex systems** is like the study of non-elephant biology.”* —??
 - complex systems have their own “elephant” species, too: dynamical systems that can be described by diff. eqs or statistical laws
 - many real-world complex systems do not obey neat macroscopic laws

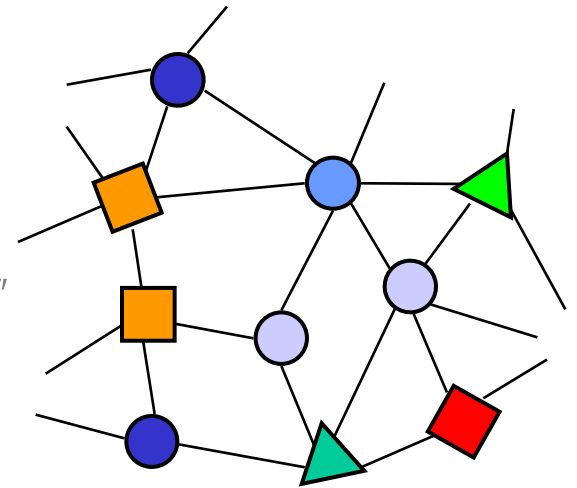


Why multi-agent modeling?

➤ Equations and laws can be hard or impossible to find in...

morphogenesis

- ✓ systems that *no macroscopic quantity* suffices to explain ~~(ODE)~~
 - no law of “concentration”, “pressure”, or “gross domestic product”
 - even if global metrics can be designed to give an indication about the system’s dynamical regimes, they rarely obey a given equation or law
- ✓ systems that require a *non-Cartesian* decomposition of space ~~(PDE)~~
 - network of irregularly placed or mobile *agents*
- ✓ systems that contain *heterogeneity*
 - segmentation into different *types of agents*
 - at a fine grain, this would require a “patchwork” of regional equations
- ✓ systems that are dynamically *adaptive*
 - the topology and strength of the interactions depend on the short-term activity of the agents and long-term “fitness” of the system in its environment



Different approaches and families of models

➤ Biological, bio-inspired or artificial models

✓ focused on spatial differentiation patterns (little or no motion)

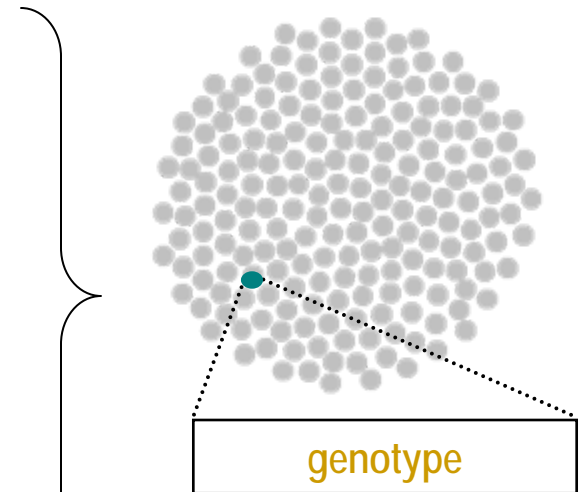
- reaction-diffusion (PDEs, cellular automata)
- gene networks (Boolean or concentrations) on a fixed lattice
- "amorphous computing"

✓ focused on motion (little or no patterning)

- Cellular Potts Model (on predefined cell types)
- aggregation, self-assembly
- collective motion, flocking, cellular sorting

✓ at different scales

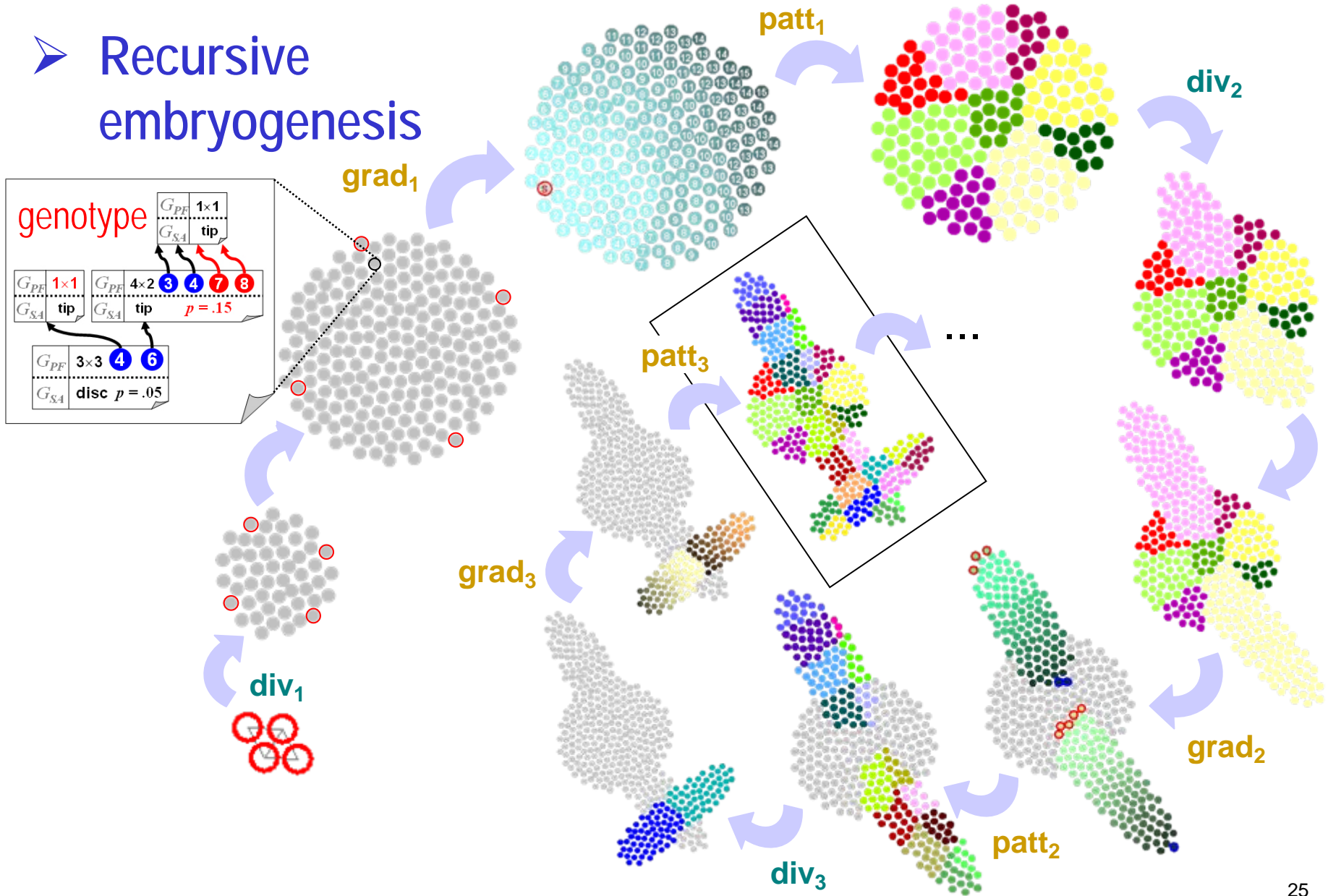
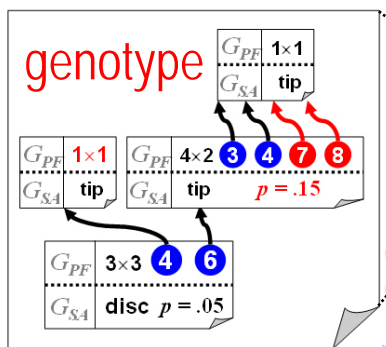
- macroscopic models (densities, differential geometry) → no individual information
- mesoscopic models (cellular centers, Potts) → no membrane geometry or nuclei
- microscopic models (elastic polyedra, drop models) → cellular deformations

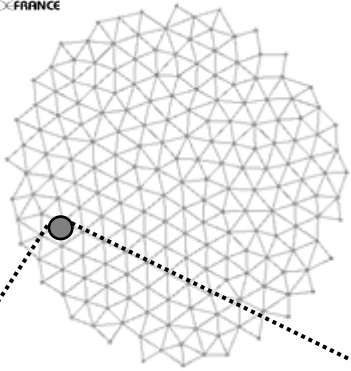


a combination that is still rare ; but see Hogeweg / Salazar-Ciudad / Mjolsness..

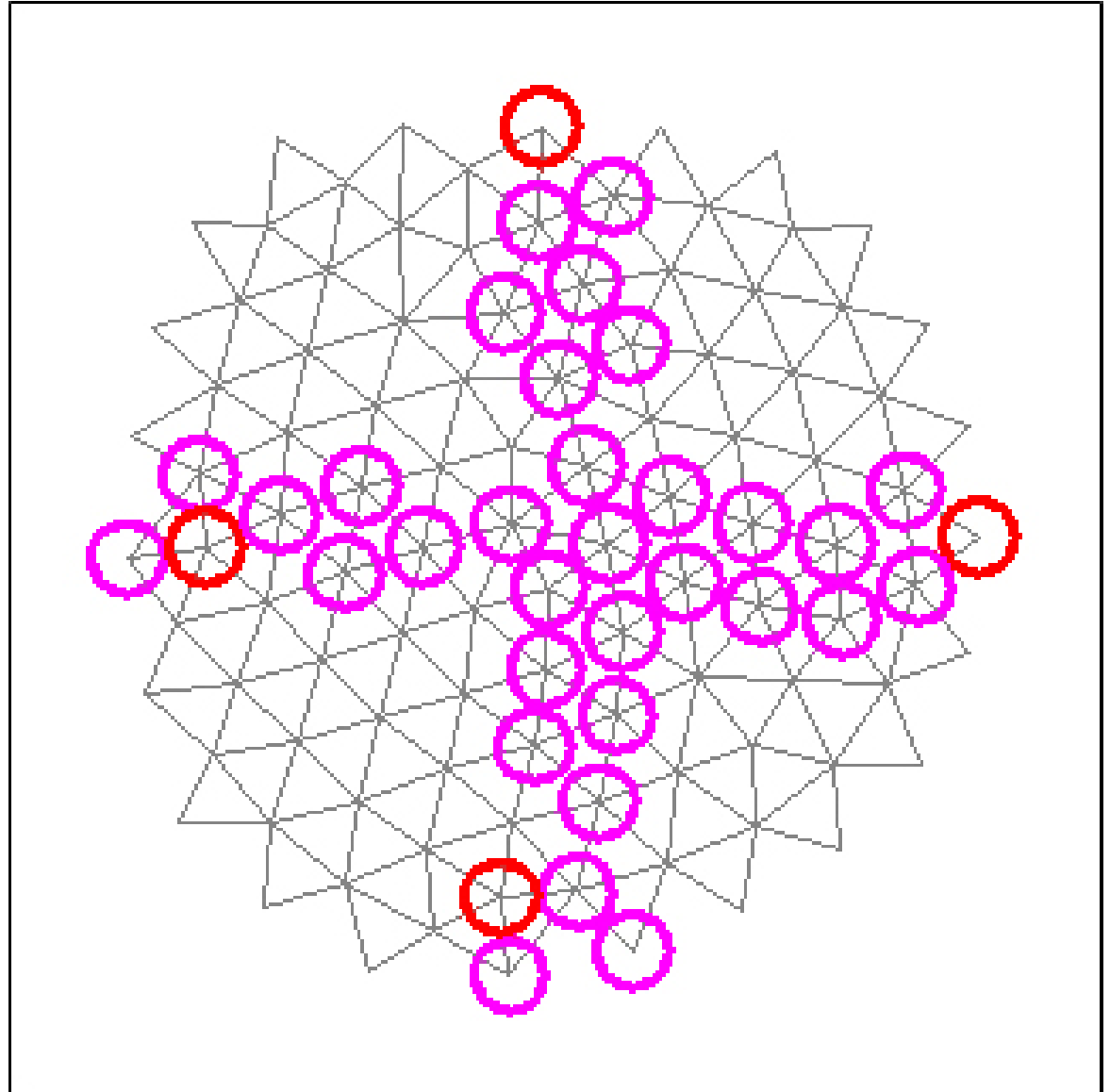
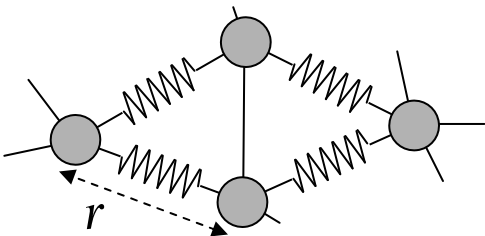
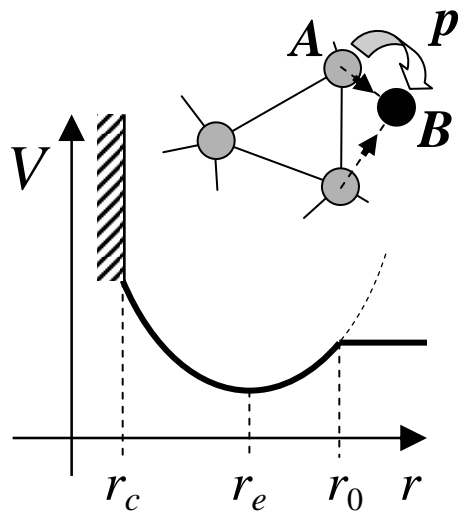
Example of hybrid mesoscopic model

Recursive embryogenesis

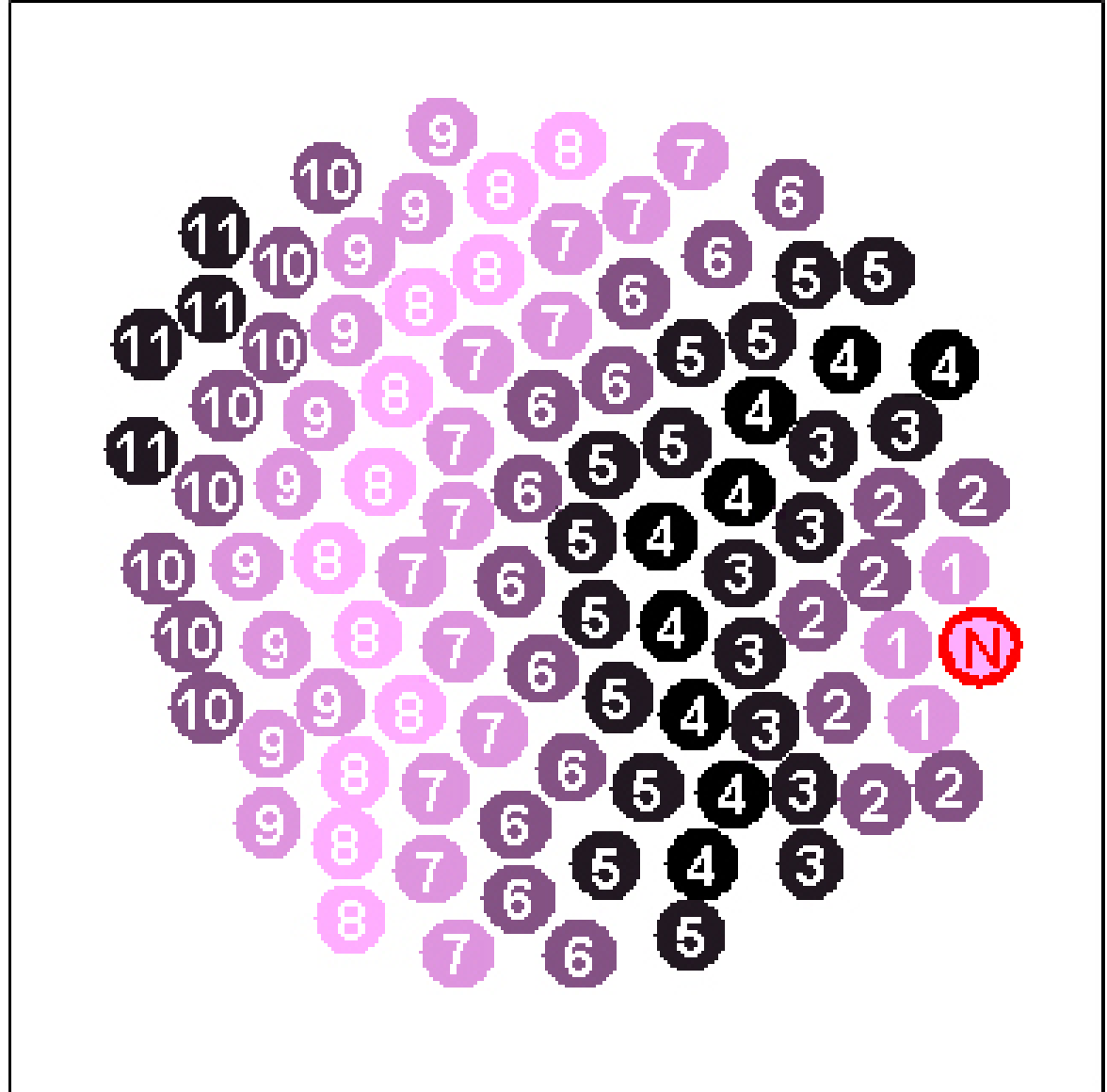
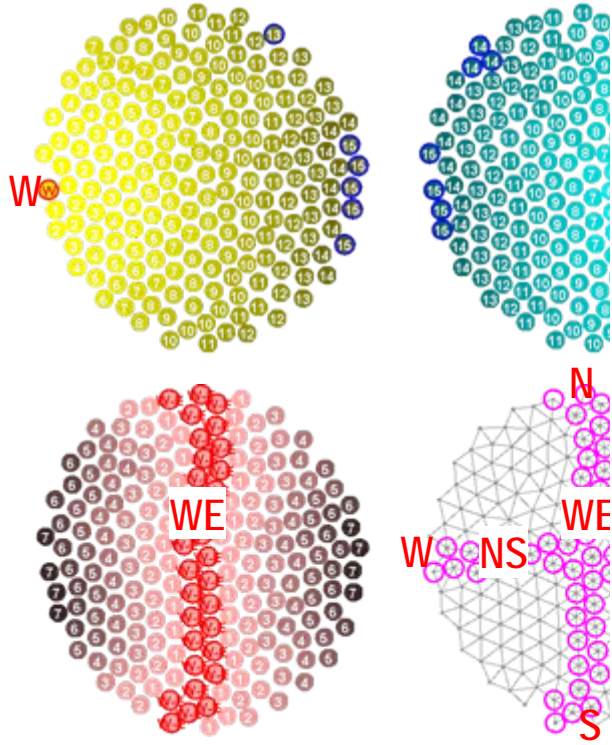


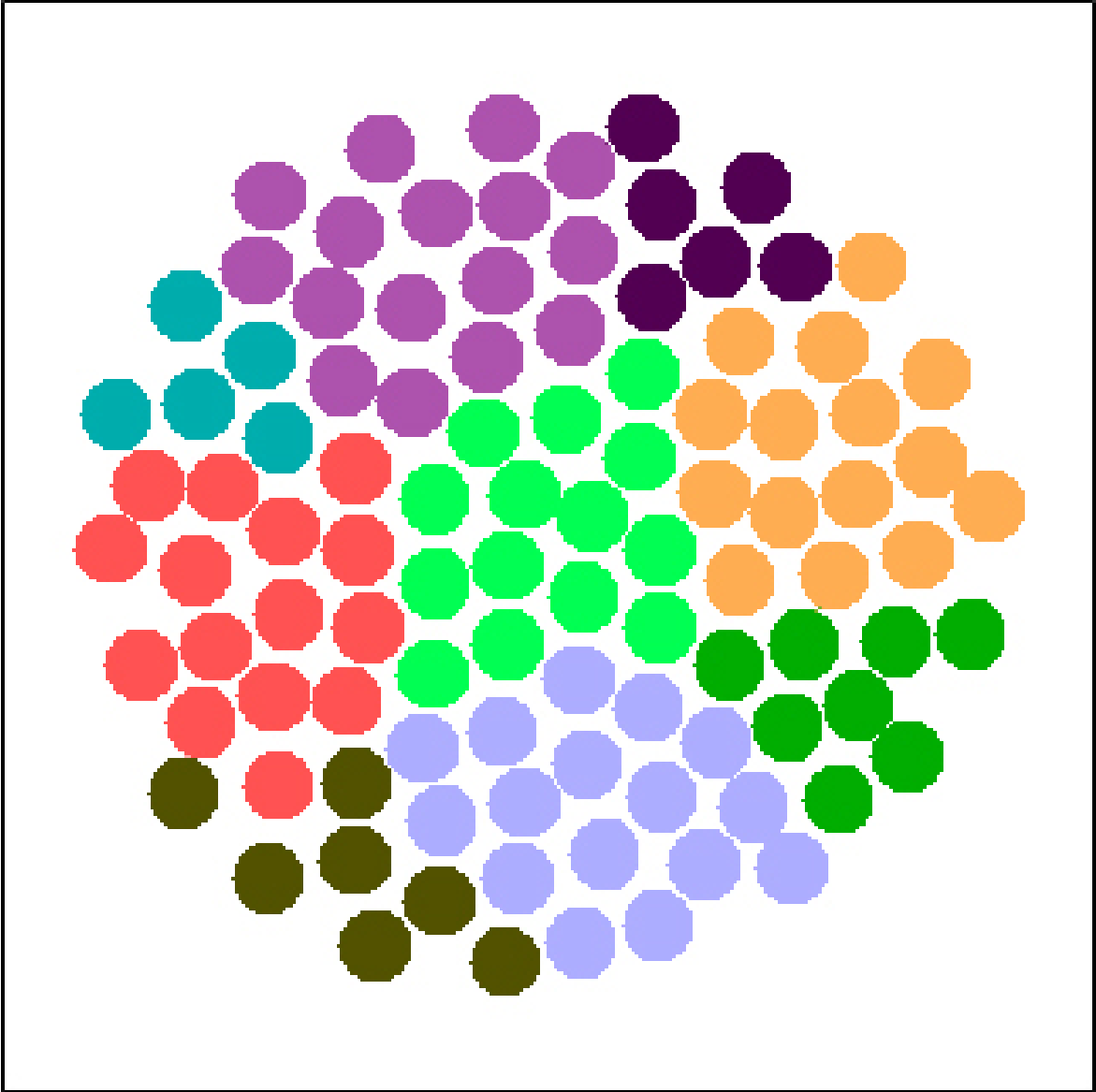
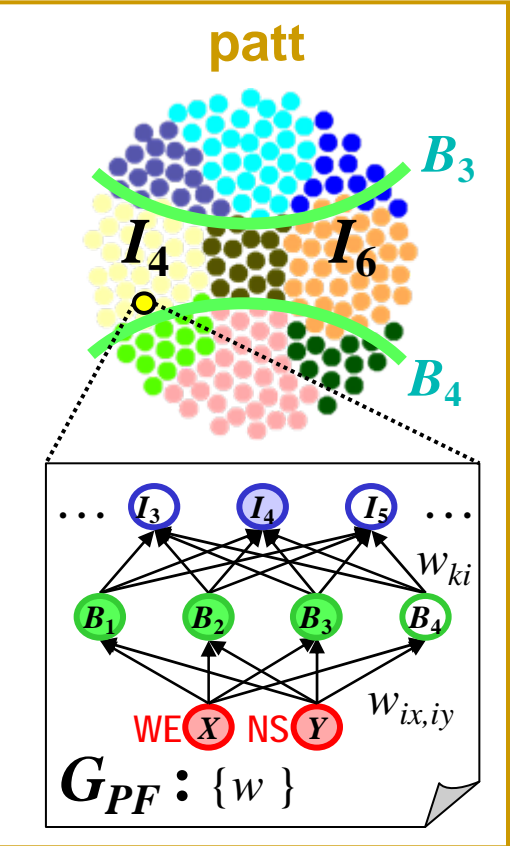


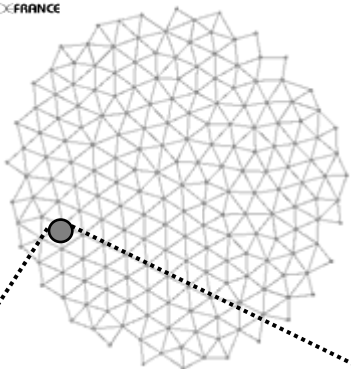
$G_{SA}: r_c < r_e = 1 \ll r_0$
 $p = 0.05$



grad

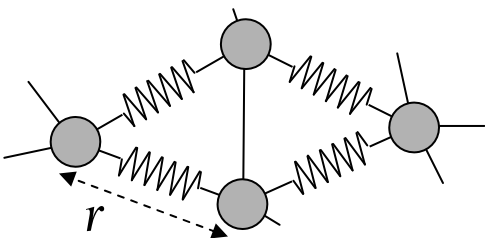
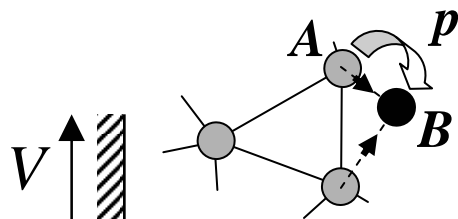




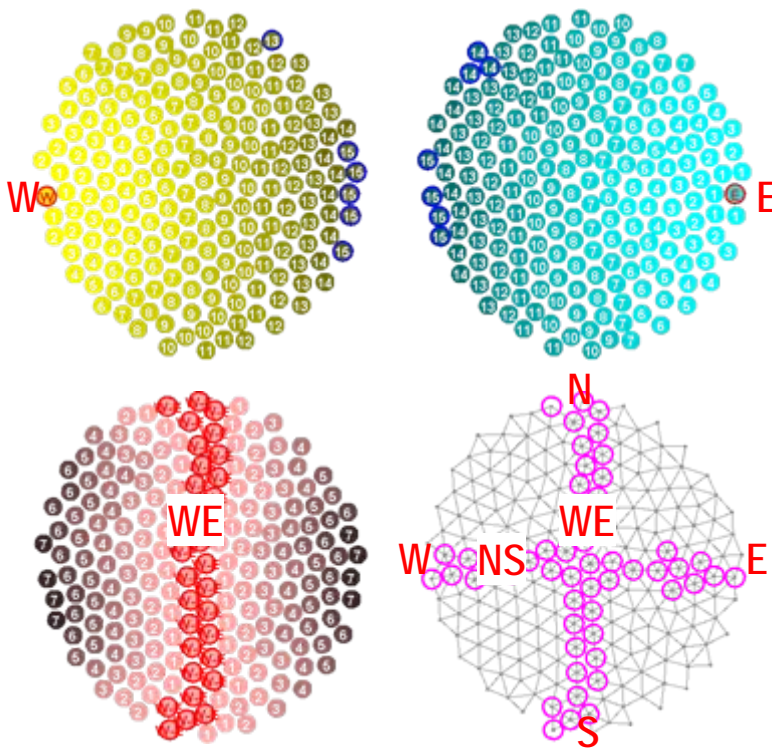


$$G_{SA} : r_c < r_e = 1 \ll r_0$$

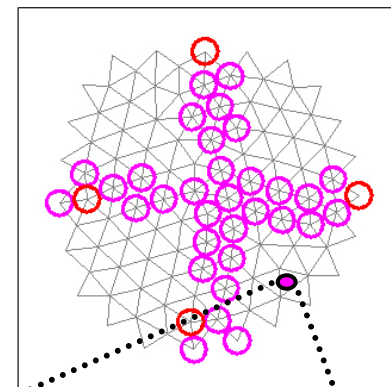
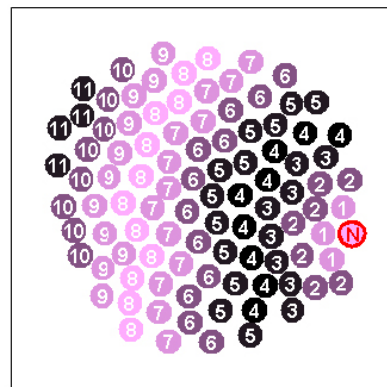
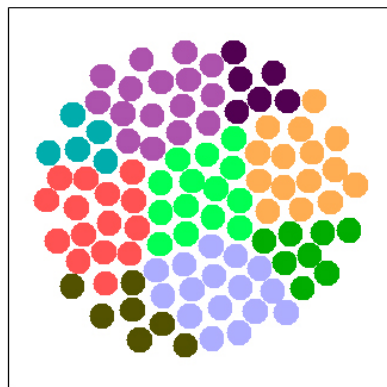
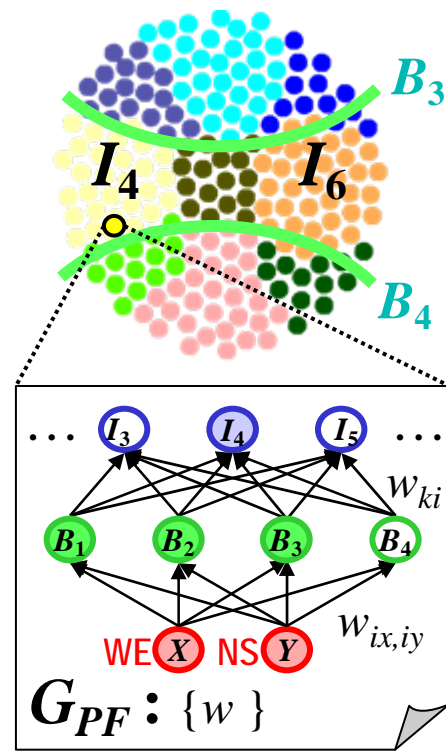
$$p = 0.05$$



grad



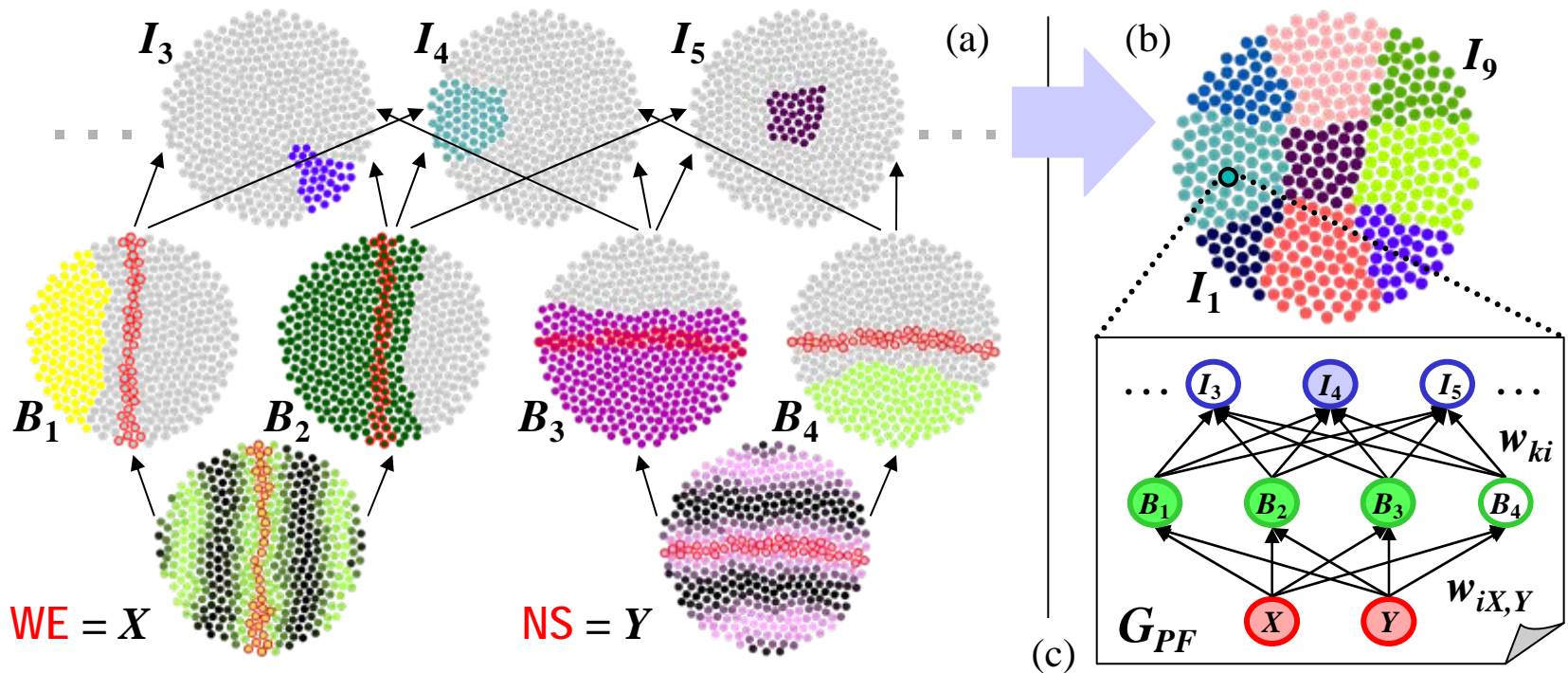
patt



$$G_{SA} \cup G_{PF}$$

Virtual gene atlas

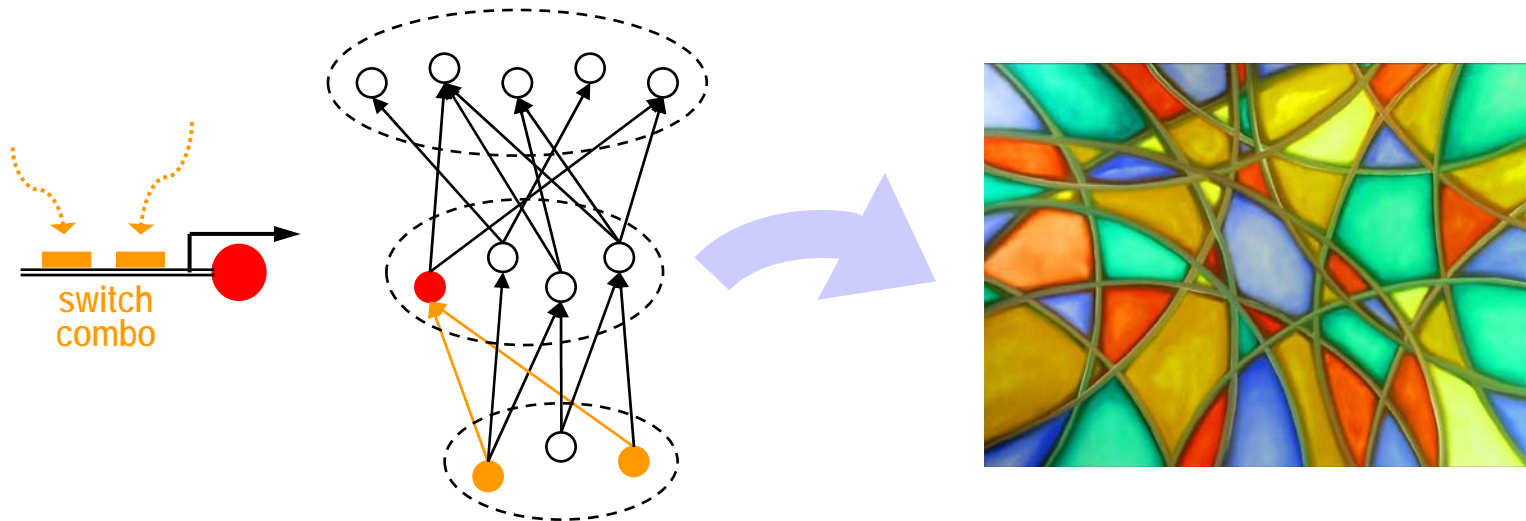
- **Programmed patterning (patt): the hidden embryo map**
 - a) same swarm in different colormaps to visualize the agents' internal patterning variables X , Y , B_i and I_k (virtual *in situ hybridization*)
 - b) consolidated view of all identity regions I_k for $k = 1 \dots 9$
 - c) gene regulatory network used by each agent to calculate its expression levels, here: $B_1 = \sigma(1/3 - X)$, $B_3 = \sigma(2/3 - Y)$, $I_4 = B_1 B_3 (1 - B_4)$, etc.



From feedforward to recurrent gene regulation

➤ Summary: simple feedforward hypothesis

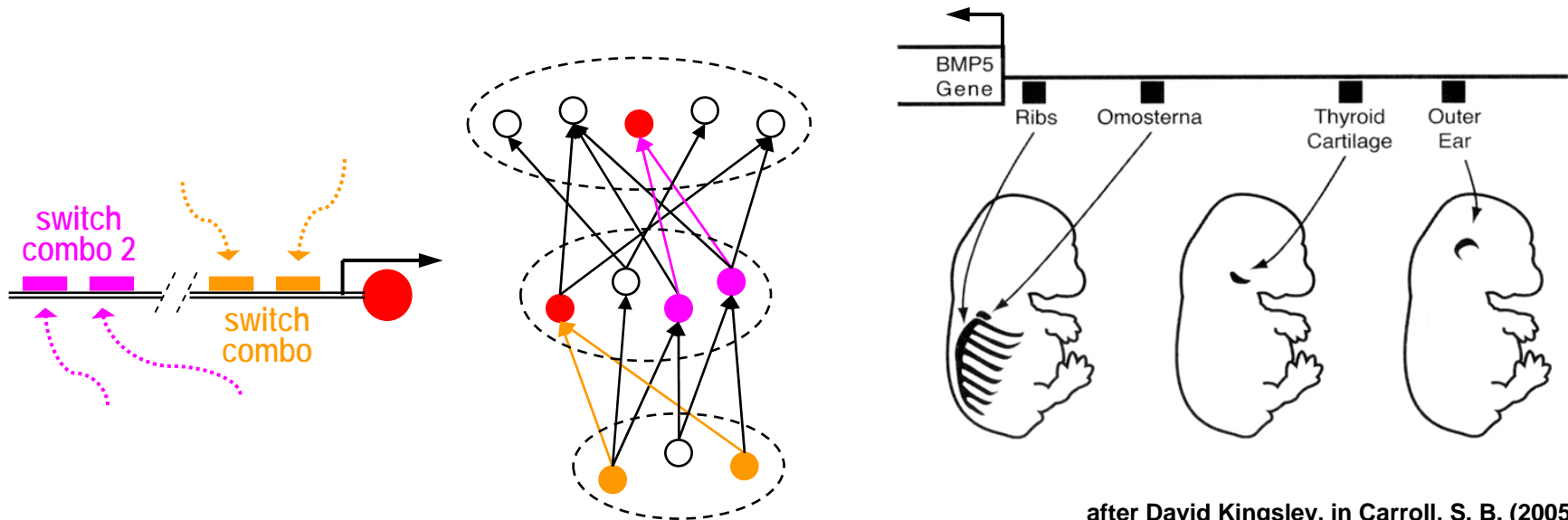
- ✓ developmental genes are broadly organized in tiers, or “generations”: earlier genes map the way for later genes
- ✓ gene expression propagates in a directed fashion: first, positional morphogens create domains, then domains intersect



From feedforward to recurrent gene regulation

➤ Toolkit genes are often multivalent

- ✓ exception to the feedforward paradigm: "toolkit" genes that are reused at different stages and different places in the organism
- ✓ however, a toolkit gene is triggered by different switch combos, which can be represented by duplicate nodes in different tiers

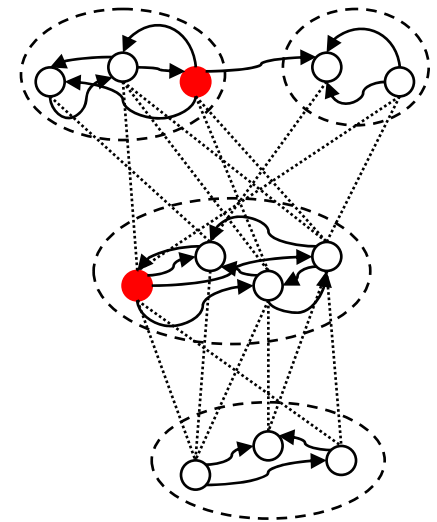
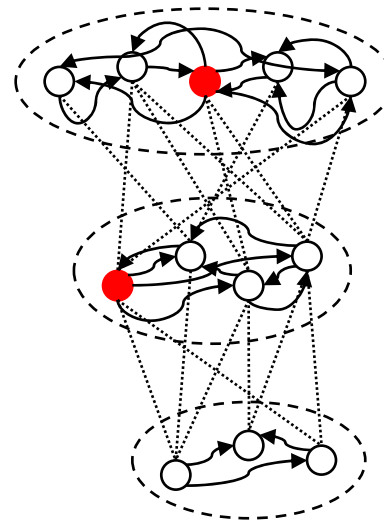
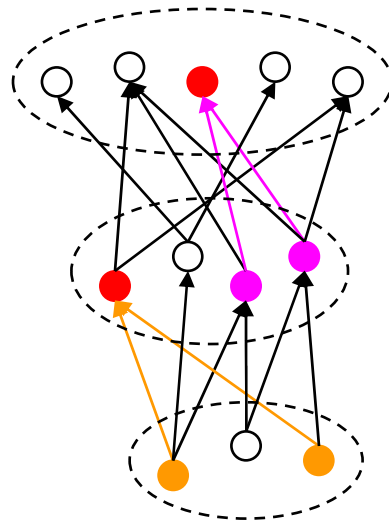
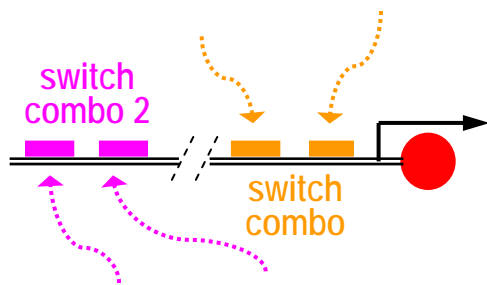


after David Kingsley, in Carroll, S. B. (2005)
Endless Forms Most Beautiful, p125

From feedforward to recurrent gene regulation

➤ More realistic variants of GRNs

- ✓ add recurrent links within tiers → domains are not established independently but influence and sharpen each other
- ✓ subdivide tiers into subnetworks → this creates **modules** that can be reused and starts a hierarchical architecture



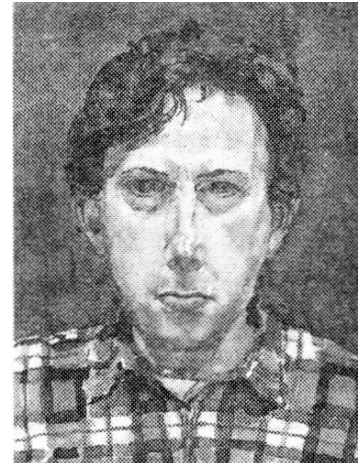
Multiscale embryogenesis

➤ Morphological refinement by iterative growth

- ✓ details are not created in one shot, but gradually added. . .

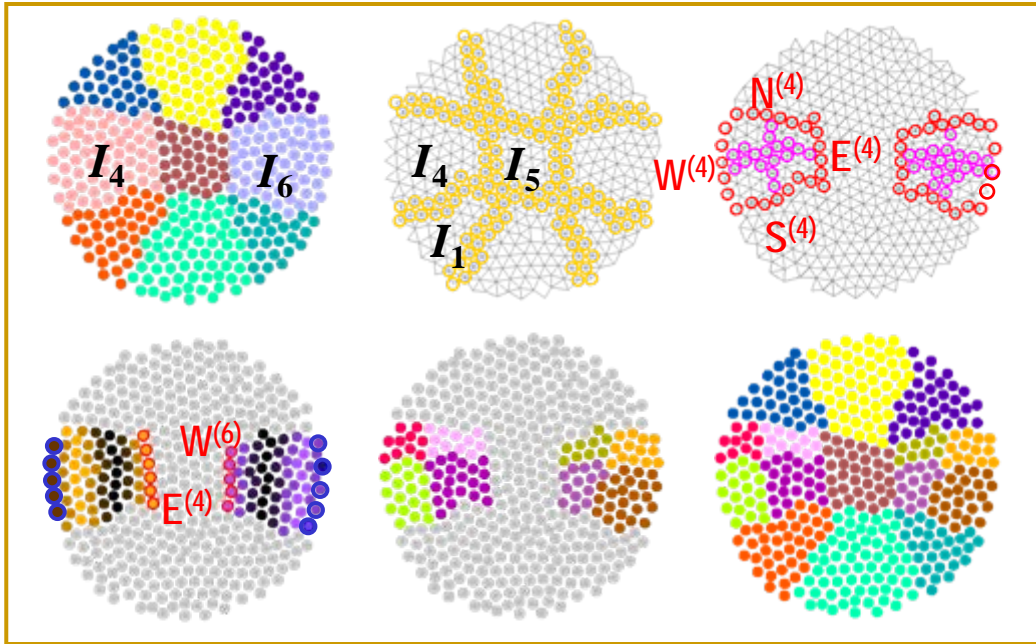


- ✓ . . . while, at the same time, the canvas grows

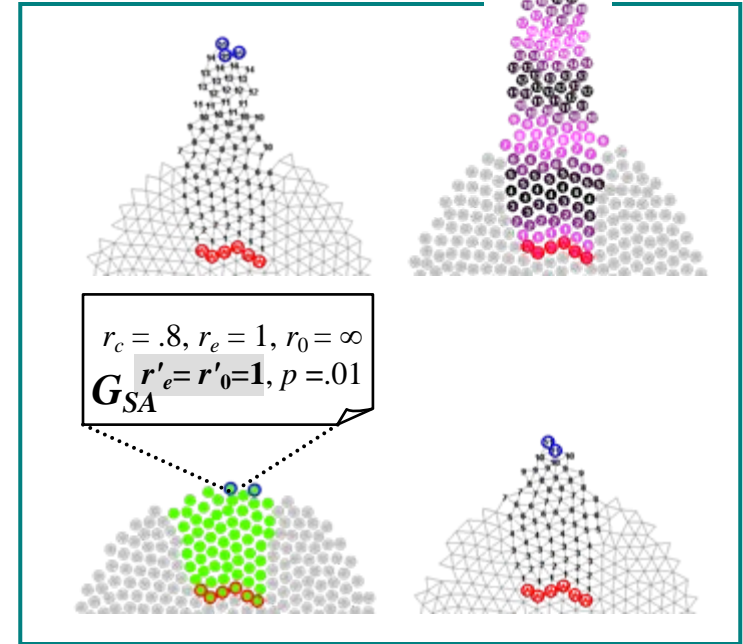
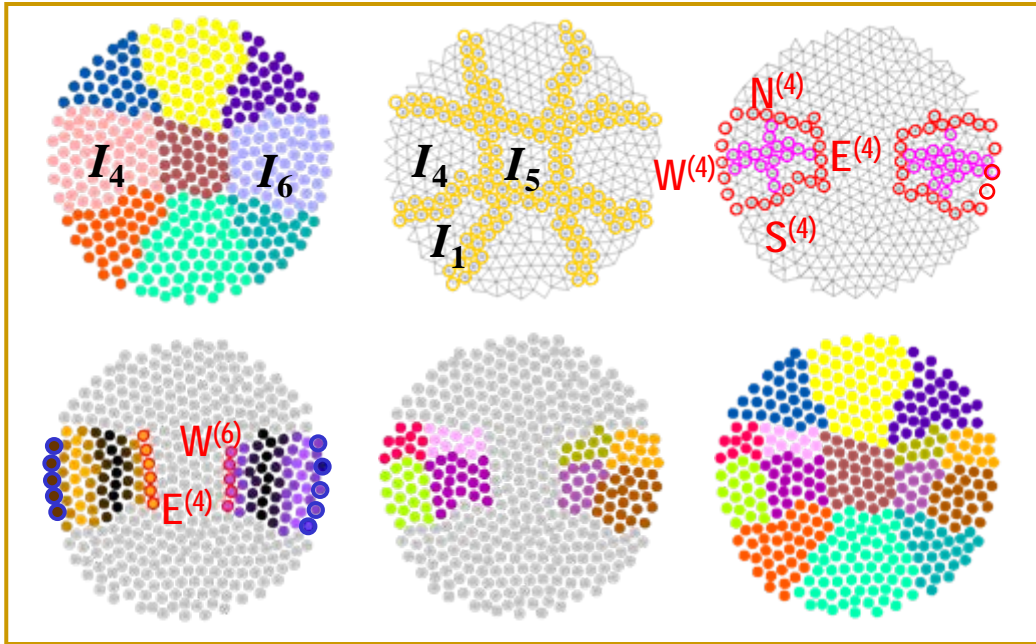


from Coen, E. (2000)
The Art of Genes, pp131-135

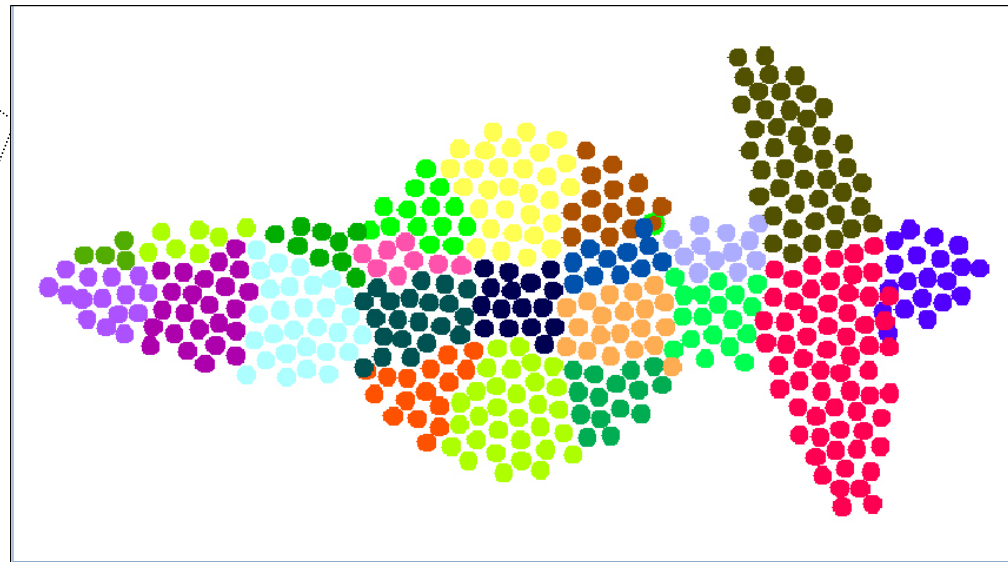
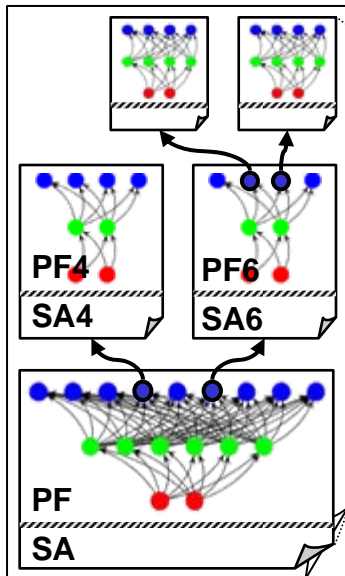
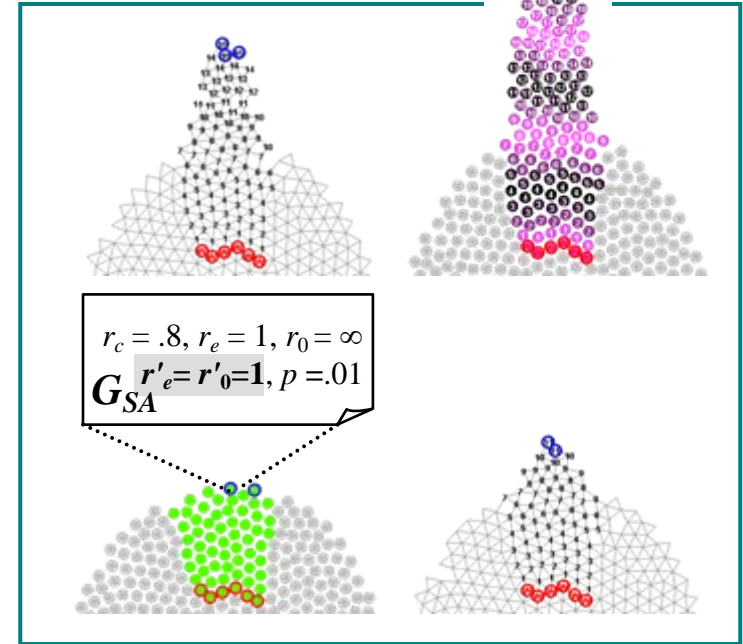
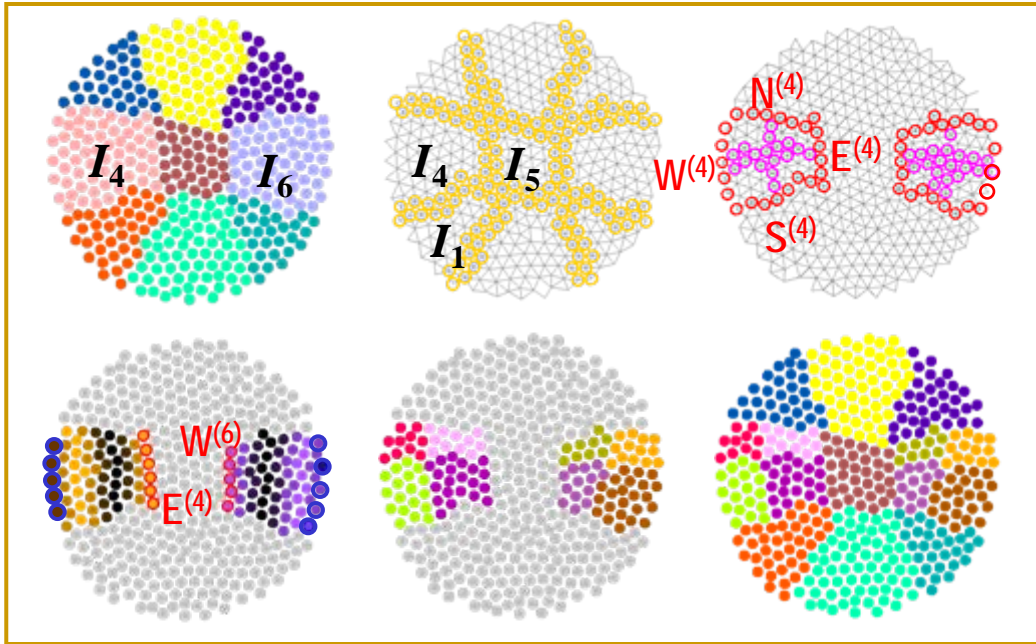
Multiscale embryogenesis



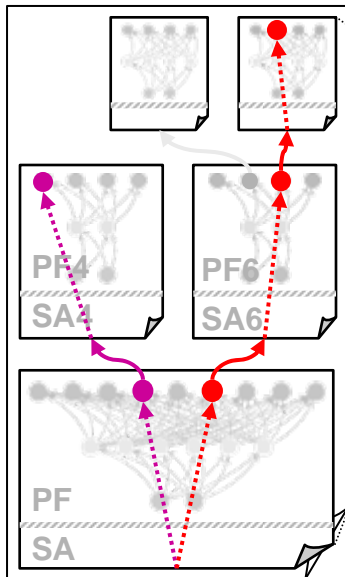
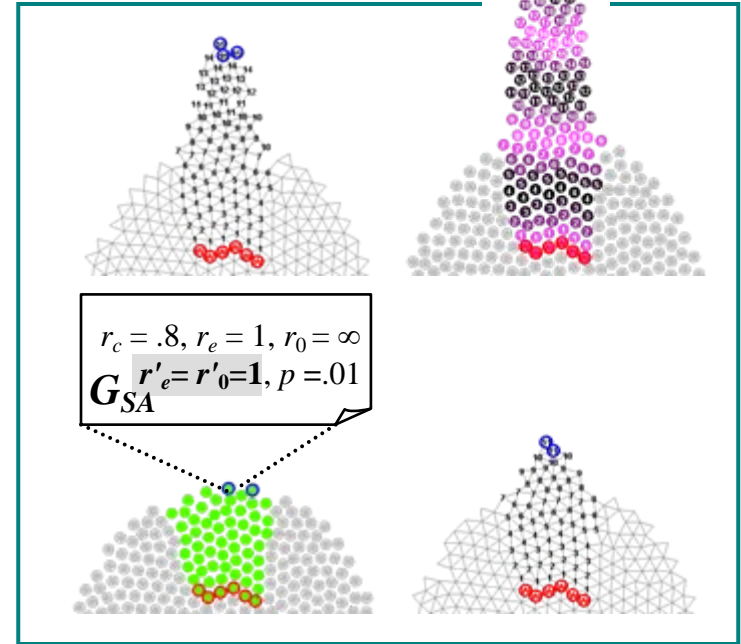
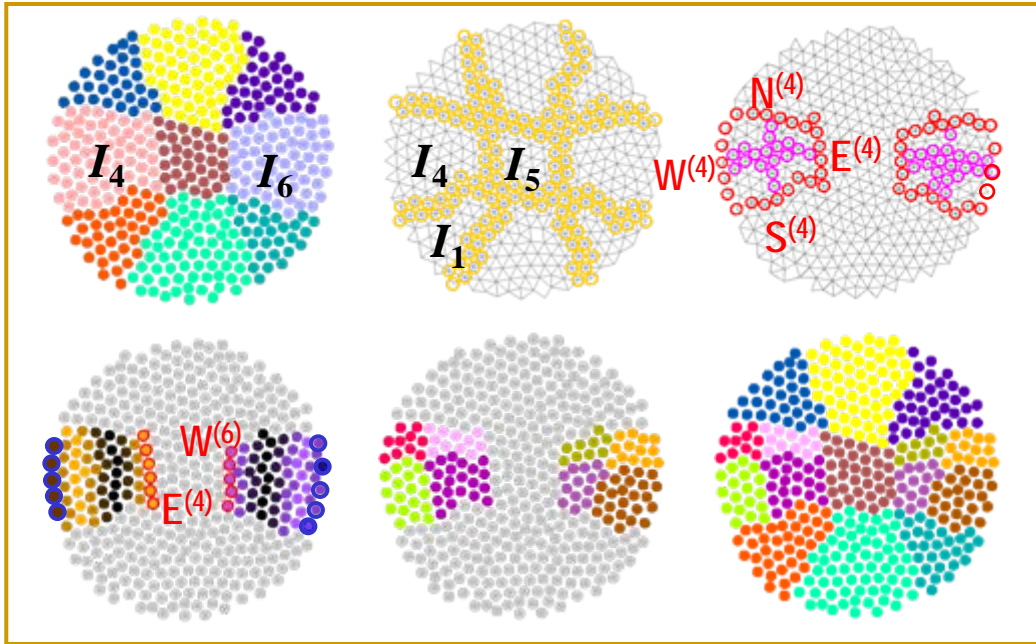
Multiscale embryogenesis



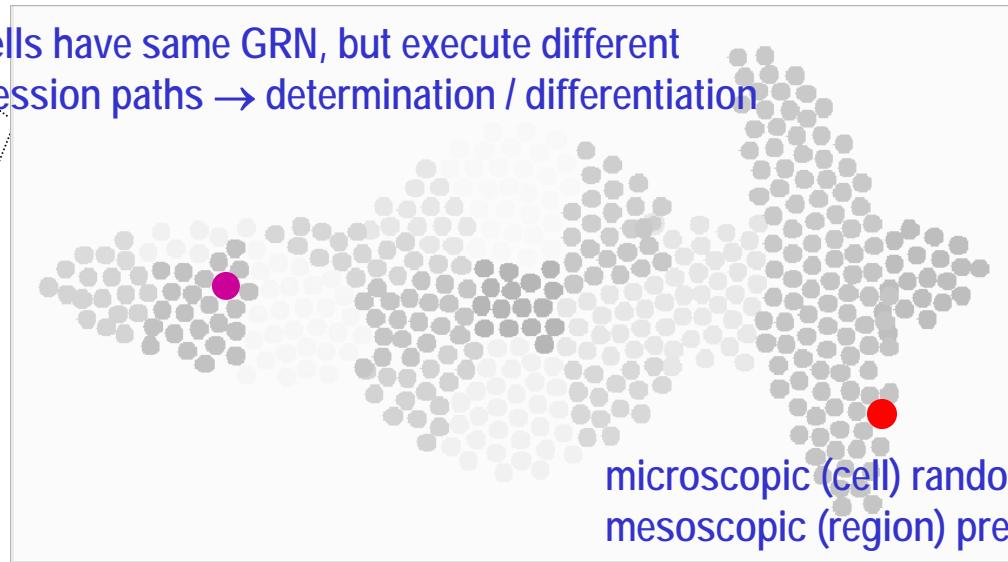
Multiscale embryogenesis



Multiscale embryogenesis



all cells have same GRN, but execute different expression paths → determination / differentiation



microscopic (cell) randomness, but mesoscopic (region) predictability

The self-made puzzle of embryogenesis

1. Self-organized and structured systems
2. A two-side challenge: heterogeneous motion / moving patterns
3. A multi-agent model of embryogenesis
4. Evolutionary development (evo-devo)

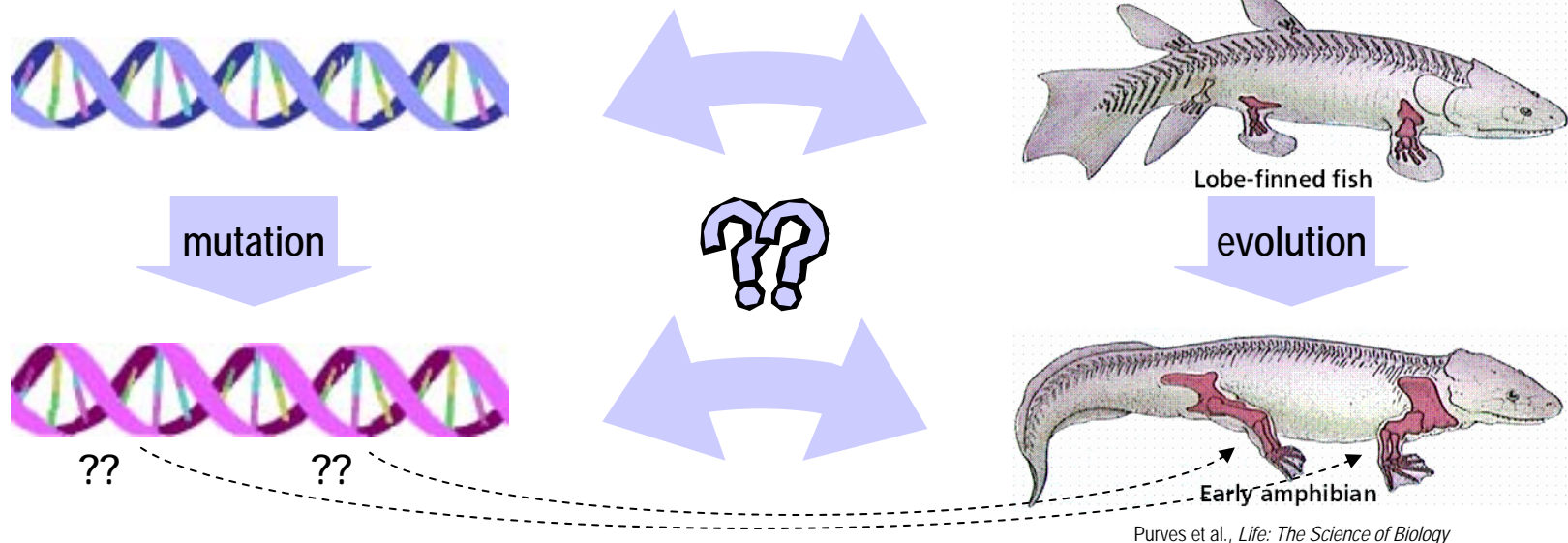
Evolutionary innovation by development

➤ Development: the missing link of the Modern Synthesis

"When Charles Darwin proposed his theory of evolution by variation and selection, explaining selection was his great achievement. He could not explain variation. That was Darwin's dilemma."

*"To understand novelty in evolution, **we need to understand organisms down to their individual building blocks, down to their deepest components, for these are what undergo change.**"*

—Marc W. Kirschner and John C. Gerhart (2005)
The Plausibility of Life, p. ix



The self-made puzzle of “evo-devo” engineering

➤ Development: the missing link of the Modern Synthesis

Amy L. Rawson
www.thirdroar.com

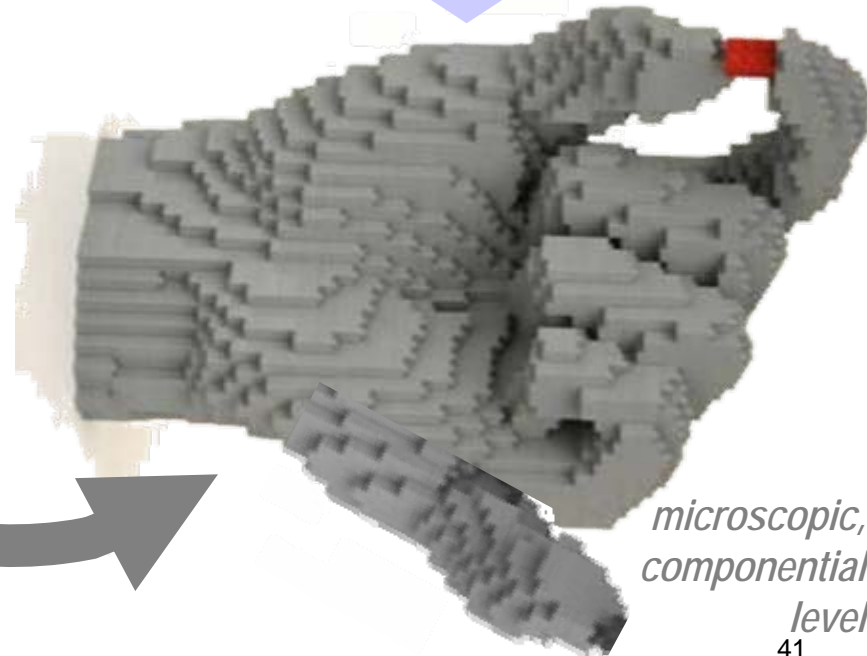


*macroscopic,
emergent level*

“To understand novelty in evolution, we need to understand organisms down to their individual building blocks, down to their deepest components, for these are what undergo change.”



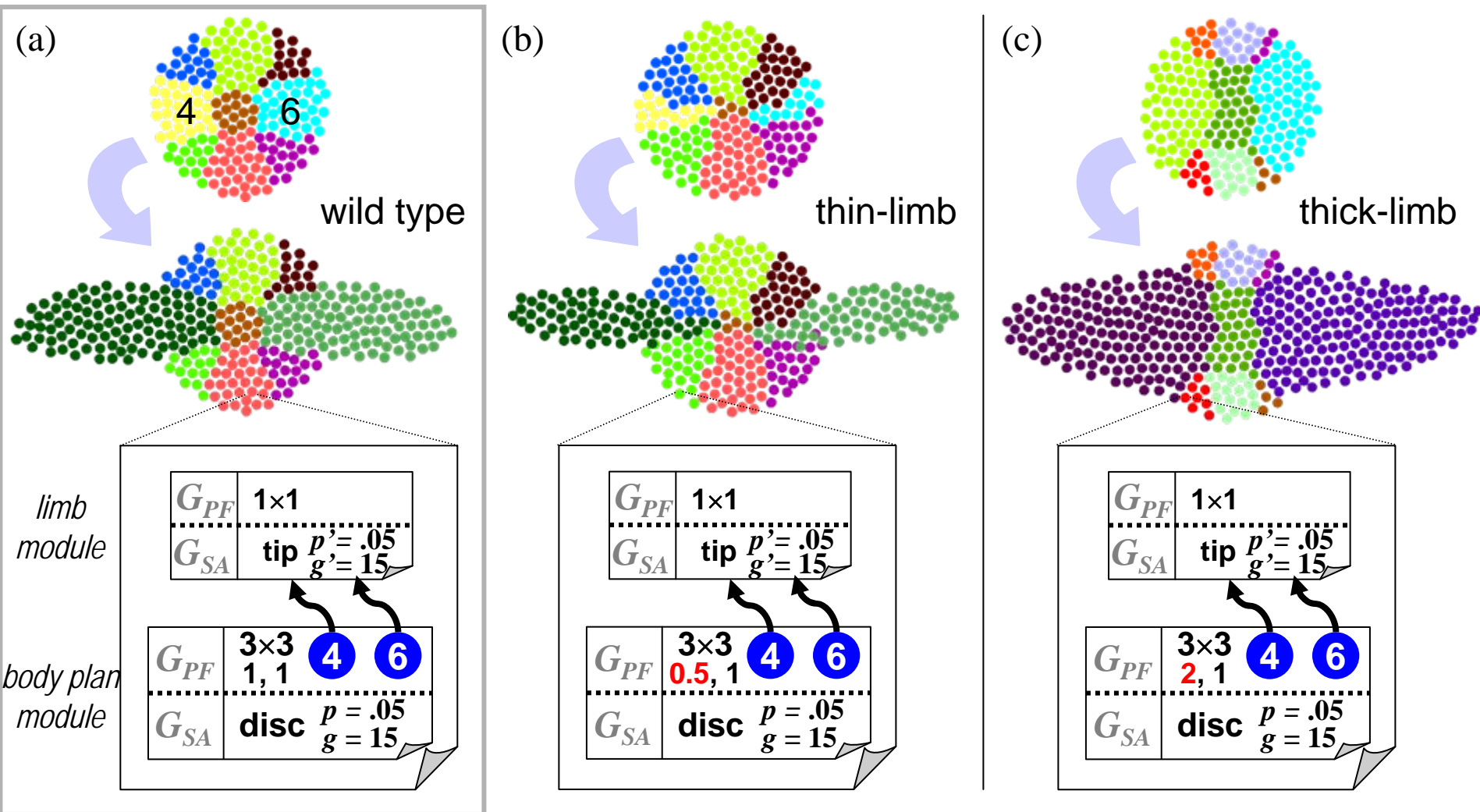
Nathan Sawaya
www.brickartist.com



*microscopic,
componential
level*

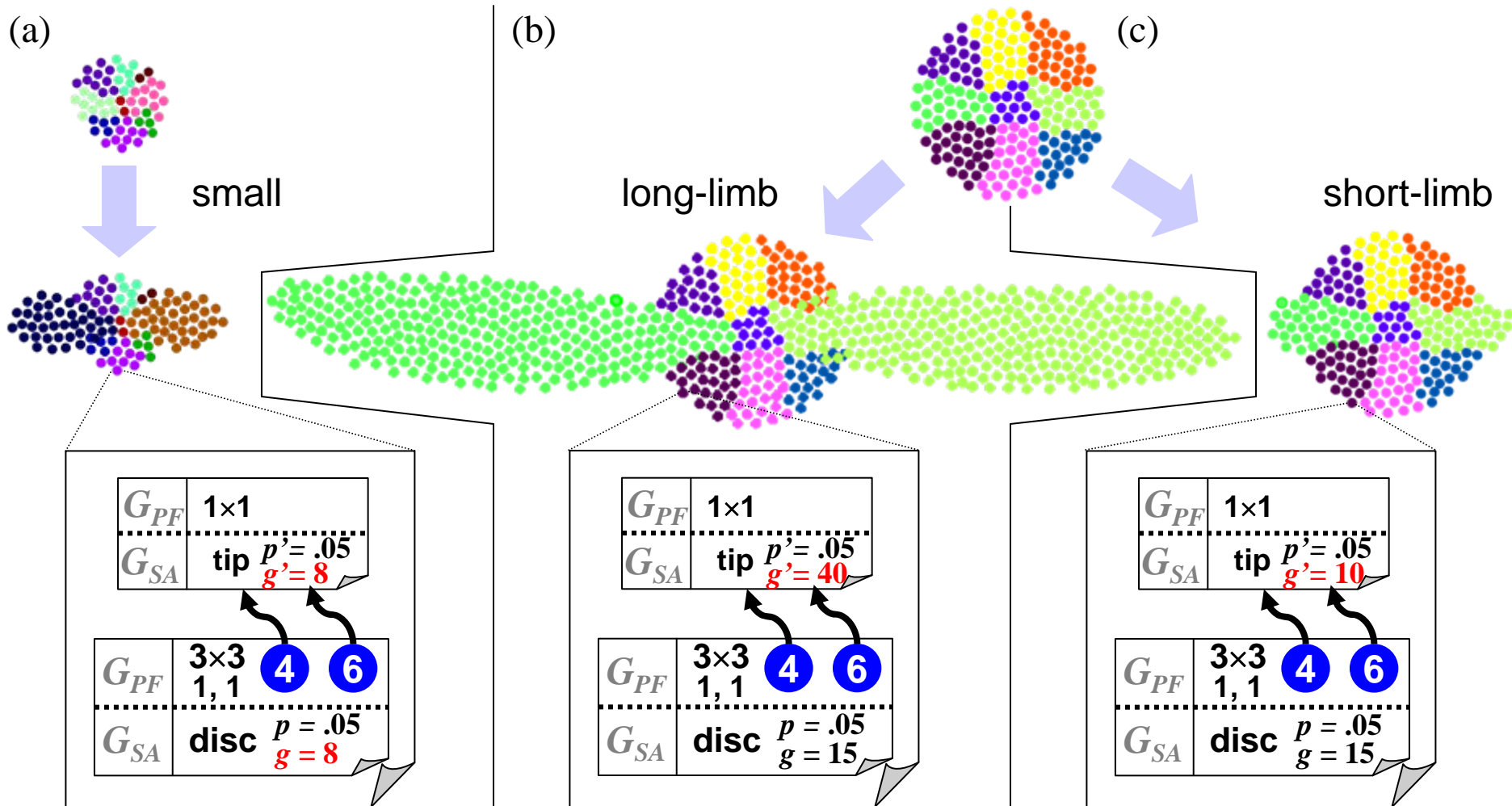
Multi-agent evolutionary development (evo-devo)

➤ Quantitative mutations: limb thickness



Multi-agent evolutionary development (evo-devo)

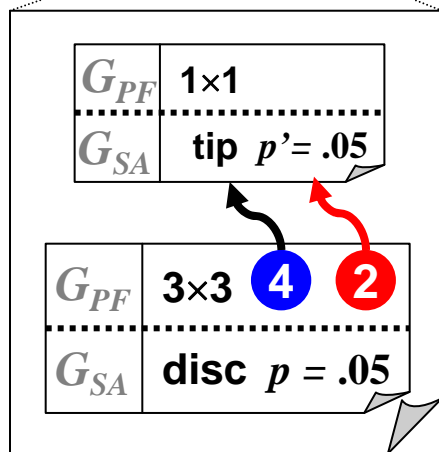
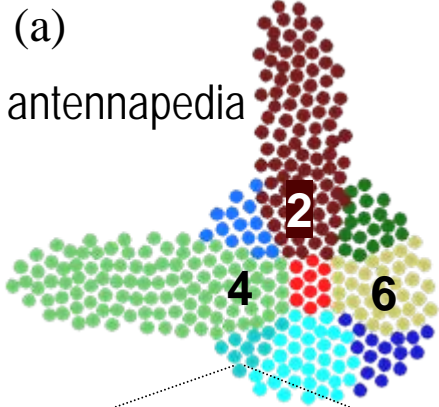
Quantitative mutations: body size and limb length



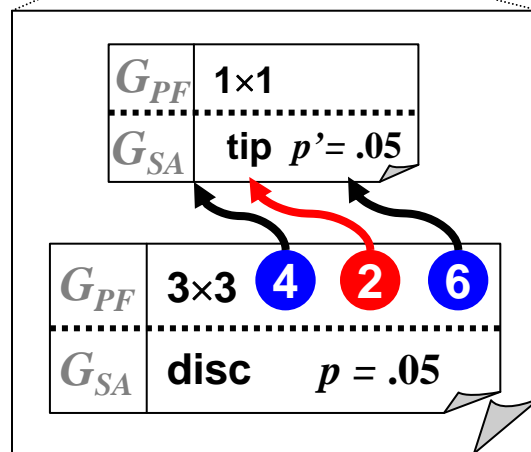
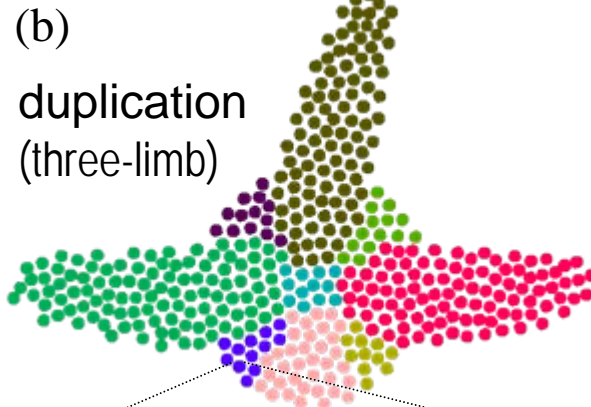
Multi-agent evolutionary development (evo-devo)

➤ Qualitative mutations: limb position and differentiation

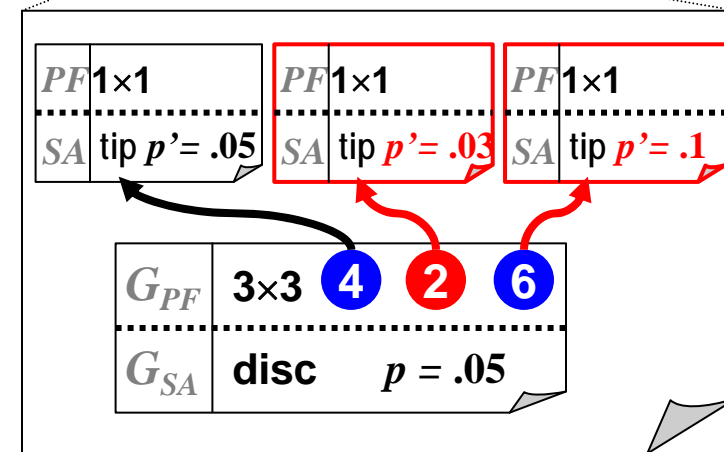
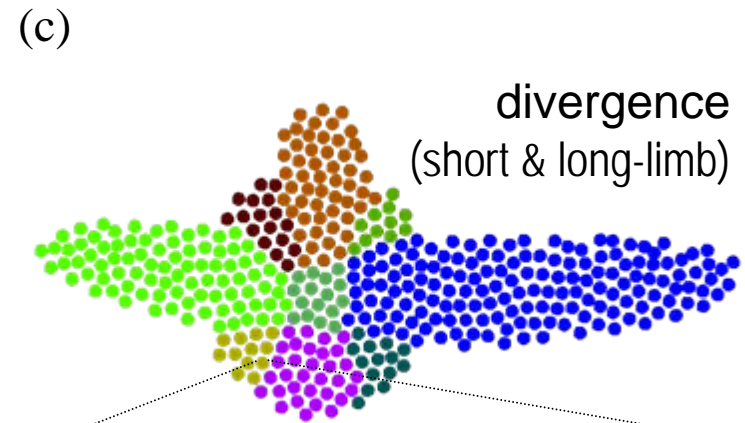
antennapedia



homology by duplication

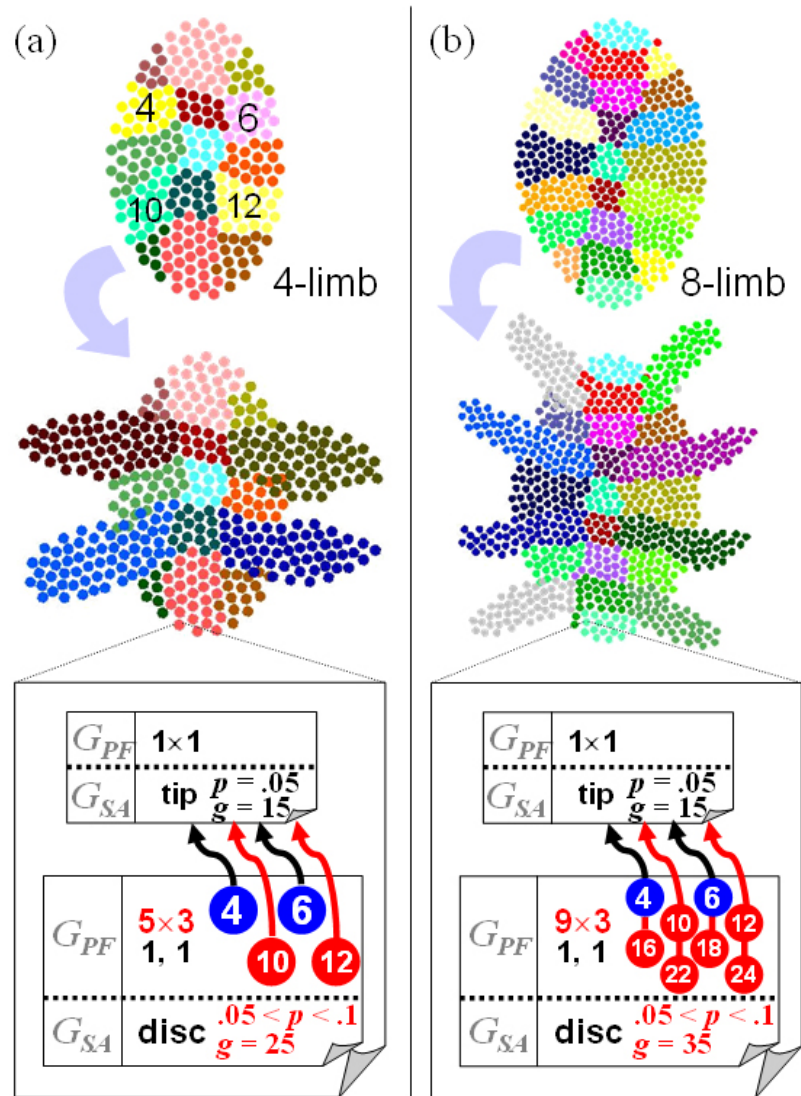


divergence of the homology



Multi-agent evolutionary development (evo-devo)

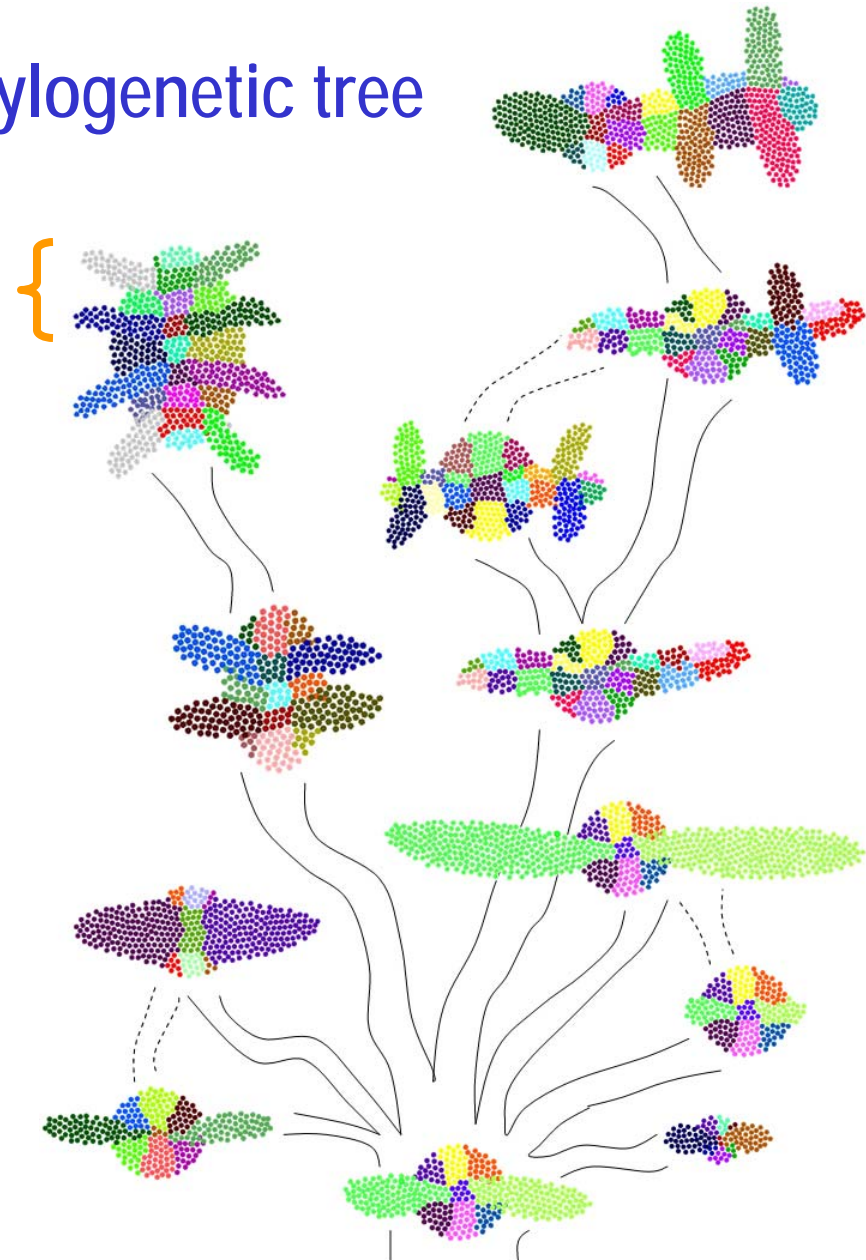
➤ Qualitative mutations: number of limbs



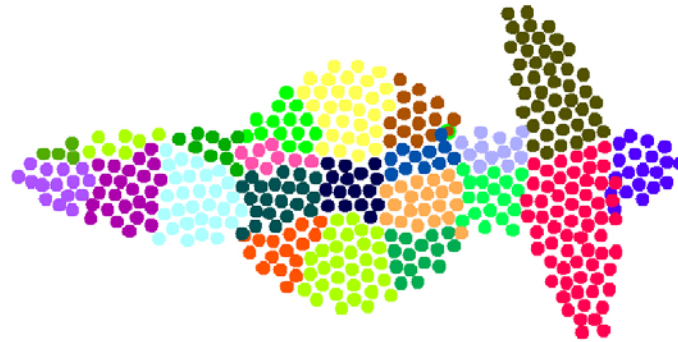
Multi-agent evolutionary development (evo-devo)

➤ Artificial phylogenetic tree

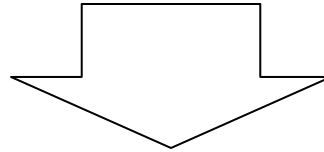
*production
of structural
innovation*



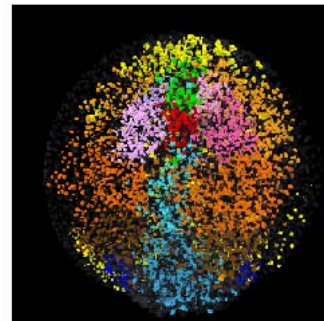
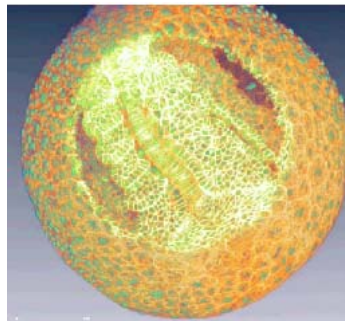
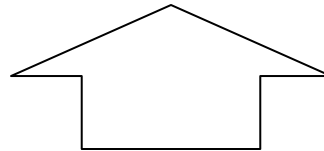
Work toward more accurate biological modeling



top-down, abstract,
heuristic approach



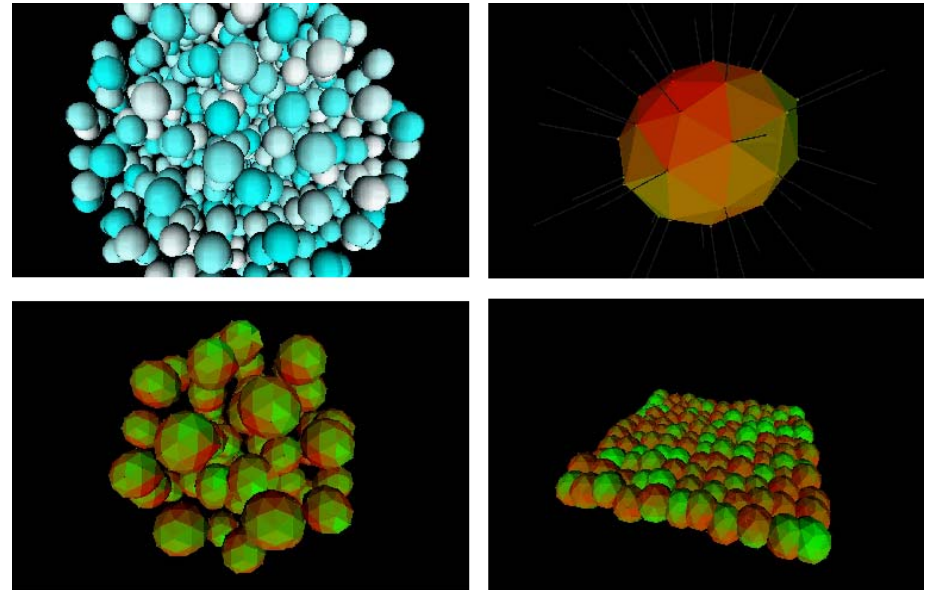
bottom-up, data-driven,
induction approach



Work toward more accurate biological modeling

➤ More accurate mechanics

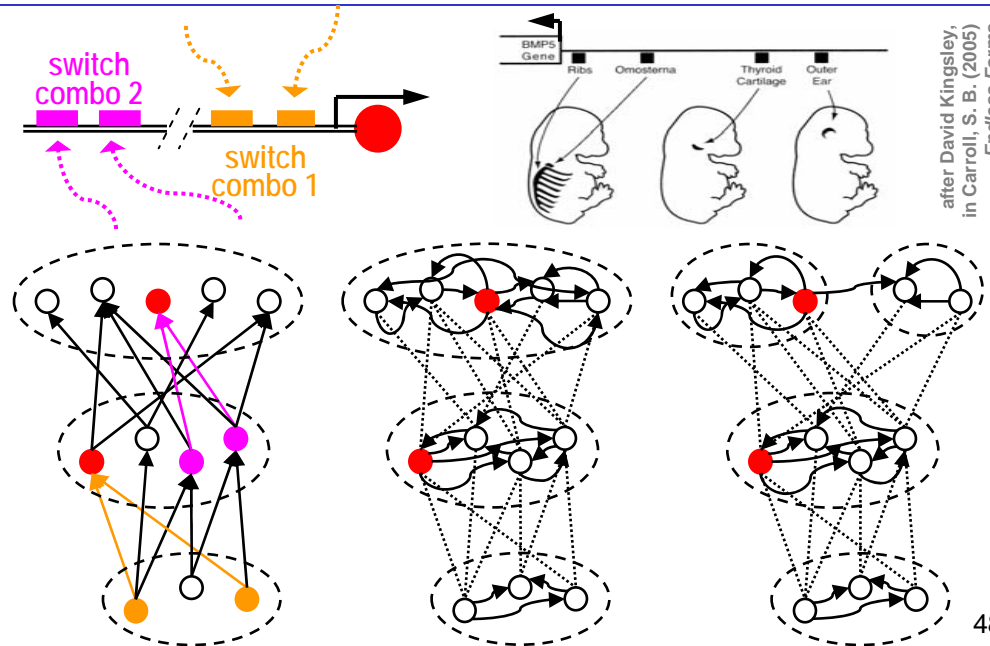
- ✓ 3-D
- ✓ individual cell shapes
- ✓ collective motion, migration
- ✓ adhesion



(Deille, Doursat, Peyrferas)

➤ Better gene regulation

- ✓ recurrent links
- ✓ gene reuse
- ✓ kinetic reaction ODEs
- ✓ attractor dynamics



after David Kingsley, in Carroll, S. B. (2005) *Endless Forms Most Beautiful*, p125

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