

SPIN-ONE POLARIZATION VECTORS

Particle at rest with spin projection referred to the z-axis:

$$\underline{\epsilon}_R^\mu = (0, \underline{\epsilon}_R) \text{ where } \underline{\epsilon}_R(\pm 1) = \frac{1}{\sqrt{2}} (\mp 1, -i, 0)$$

$$\underline{\epsilon}_R(0) = (0, 0, 1)$$

where $\underline{\epsilon}_R$ are orthonormal eigenvectors of $S_z = \begin{pmatrix} 0 & -i & 0 \\ i & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$.

Particle at rest with spin projection referred to an arbitrary direction (θ, ϕ) :

$$\underline{\epsilon}_R(\pm 1) = \frac{e^{\pm i\phi}}{\sqrt{2}} (\mp \cos\theta \cos\phi + i \sin\phi, \mp \cos\theta \sin\phi - i \cos\phi, \pm \sin\theta)$$

$$\underline{\epsilon}_R(0) = (\sin\theta \cos\phi, \sin\theta \sin\phi, \cos\theta)$$

A general polarization vector ϵ^μ can be obtained by boosting the polarization vectors at rest $\underline{\epsilon}_R^\mu$.

$$\epsilon^\mu(p, \lambda) = \left(\frac{p \cdot \underline{\epsilon}_R}{m}, \underline{\epsilon}_R + \left(\frac{E-m}{m} \right) \hat{p} \frac{p \cdot \underline{\epsilon}_R}{p} \right)$$

where m is the mass, $E = \sqrt{p^2 + m^2}$ and $\hat{p} = \frac{p}{|p|}$.

The HELICITY polarization vectors are obtained by boosting along the spin polarization axis. One obtains:

$$\epsilon_H^\mu(p, \lambda) \Rightarrow \text{HELICITY pol. vectors}$$

$$\epsilon_H^\mu(p, \pm 1) = \frac{e^{\pm i\phi}}{\sqrt{2}} (0, \mp \cos\theta \cos\phi + i \sin\phi, \mp \cos\theta \sin\phi - i \cos\phi, \pm \sin\theta) = (0, \underline{\epsilon}_R)$$

$$\epsilon_H^\mu(p, 0) = \left(\frac{p}{m}, \frac{E}{m} \hat{p} \right) = \frac{1}{m} (p, E \sin\theta \cos\phi, E \sin\theta \sin\phi, E \cos\theta)$$

APPENDIX 1: VECTOR SPHERICAL HARMONICS

The vector spherical harmonics $\{\vec{Y}_{j\ell m}(\hat{n})\}$ are very useful functions for describing vector fields confined to a cavity. They are defined as the Clebsch-Gordon product of ordinary spherical harmonics $\{Y_{\ell m}\}$ and the spin one spherical unit vectors $\{\vec{e}_m\}$:

$$\vec{Y}_{j\ell m}(\hat{n}) = \sum_{\ell'} \langle \ell' 1, m - \ell' | j m \rangle Y_{\ell'}(\hat{n}) \vec{e}_{m - \ell'} \quad (\text{A1.1})$$

They are eigenfunctions of \vec{J}^2 , \vec{L}^2 , and \vec{S}^2 with eigenvalues $j(j+1)$, $\ell(\ell+1)$ and 2, respectively.

They are most useful in manipulations involving $\vec{\nabla}$ and in doing angular integrals, due to the properties [22]

$$\vec{\nabla} \cdot (f(r) \vec{Y}_{j\ell m}) = \sqrt{\frac{\ell}{2j+1}} \left(\frac{df}{dr} + \frac{\ell+1}{r} f \right) \vec{Y}_{j\ell+1 m} - \sqrt{\frac{\ell+1}{2j+1}} \left(\frac{df}{dr} - \frac{\ell}{r} f \right) \vec{Y}_{j\ell-1 m} \quad (\text{A1.2})$$

$$\vec{\nabla} \cdot (f(r) \vec{Y}_{j\ell+1 m}) = -\sqrt{\frac{\ell+1}{2j+1}} \left(\frac{df}{dr} + \frac{\ell+2}{r} f \right) \vec{Y}_{j\ell m} \quad (\text{A1.3})$$

$$\vec{\nabla} \cdot (f(r) \vec{Y}_{j\ell-1 m}) = 0 \quad (\text{A1.4})$$

$$\vec{\nabla} \cdot (f(r) \vec{Y}_{j\ell+1 m}) = \sqrt{\frac{\ell}{2j+1}} \left(\frac{df}{dr} - \frac{\ell-1}{r} f \right) \vec{Y}_{j\ell m} \quad (\text{A1.5})$$

$$\vec{\nabla} \times (f(r) \vec{Y}_{j\ell+1 m}) = i \sqrt{\frac{\ell}{2j+1}} \left(\frac{df}{dr} + \frac{\ell+2}{r} f \right) \vec{Y}_{j\ell m} \quad (\text{A1.6})$$

$$\vec{\nabla} \times (f(r) \vec{Y}_{j\ell m}) = i \sqrt{\frac{\ell+1}{2j+1}} \left\{ f \left(\frac{df}{dr} - \frac{\ell-1}{r} f \right) \vec{Y}_{j\ell+1 m} + \sqrt{j(j+1)} \left(\frac{df}{dr} + \frac{\ell+1}{r} f \right) \vec{Y}_{j\ell-1 m} \right\} \quad (\text{A1.7})$$

$$\vec{\nabla} \times (f(r) \vec{Y}_{j\ell-1 m}) = i \sqrt{\frac{\ell+1}{2j+1}} \left(\frac{df}{dr} - \frac{\ell-1}{r} f \right) \vec{Y}_{j\ell m} \quad (\text{A1.8})$$

$$\vec{Y}_{j\ell m}^* = (-)^{j+\ell+m+1} \vec{Y}_{j\ell, -m} \quad (\text{A1.9})$$

$$\int \vec{Y}_{j\ell m}^* \cdot \vec{Y}_{j'\ell'm'} d\Omega = \delta_{j'j} \delta_{\ell'\ell} \delta_{m'm} \quad (\text{A1.10})$$

A few specific $\{\vec{Y}_{j\ell m}\}$'s for small j and ℓ are

$$\vec{Y}_{100} = \frac{1}{\sqrt{4\pi}} \vec{e}_m \quad (\text{A1.11})$$

$$\vec{Y}_{110} = -i \sqrt{\frac{3}{8\pi}} \hat{r} \times \vec{e}_m \quad (\text{A1.12})$$

$$\vec{Y}_{120} = \frac{1}{\sqrt{10}} \left\{ \vec{e}_m - 3(\hat{r} \cdot \vec{e}_m) \hat{r} \right\} \quad (\text{A1.13})$$

A final useful result is the cross product of two vector spherical harmonics, which is implicit in the relation

$$\begin{aligned} \int d\Omega \vec{Y}_{j_1 \ell_1 m_1} \times (\vec{Y}_{j_2 \ell_2 m_2} \times \vec{Y}_{j_3 \ell_3 m_3}) \\ = i \sqrt{\frac{3}{2\pi}} \left[\prod_{i=1}^3 \sqrt{(2j_i+1)(2\ell_i+1)} \right] (-)^{j_1+1} \\ \cdot \begin{pmatrix} j_1 & \ell_1 & \ell_2 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} j_1 & j_2 & j_3 \\ m_1 & m_2 & m_3 \end{pmatrix} \begin{Bmatrix} j_1 & j_2 & j_3 \\ \ell_1 & \ell_2 & \ell_3 \\ 1 & 1 & 1 \end{Bmatrix} \end{aligned}$$

(A1.14) where the curly bracket is a 9-j symbol and the 3-j symbols are related to CG coefficients by

$$\langle j_1 m_1, j_2 m_2 | j_3 m_3 \rangle = (-)^{j_1-j_2-m_3} \sqrt{2j_3+1} \begin{pmatrix} j_1 & j_2 & j_3 \\ m_1 & m_2 & -m_3 \end{pmatrix} \quad (\text{A1.15})$$

... on-shell spinors are as follows:

0)

w, 0)

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where m is the mass, $E = \sqrt{p^2 + m^2}$ and $\hat{p} = |\hat{p}|$.

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$\epsilon_H^\mu(p, \lambda) \Rightarrow$ HELICITY pol. vectors

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$$\epsilon_H^\mu(p, 0) = \left(\frac{p}{m}, \frac{E}{m} \hat{p} \right) = \frac{1}{m} (p, E \sin\theta \cos\phi, E \sin\theta \sin\phi, E \cos\theta)$$

$$L = J_z = 0, 2$$

$$A \cdot L \Rightarrow A \perp$$

and hence

$$\int d\tau \vec{A}_n \cdot \vec{A}_n = \frac{1}{2\omega_n} \delta_{nn}$$

$$\int d\tau \psi_n^\dagger \psi_n = \delta_{nn}$$

b) Glucun Modes

The normalized classical glucun modes are of TE ("magnetic") and TM ("electric") type

TE

$$\vec{A}_{j,m} = \alpha_j^{TE} j_j(\omega_j r) \vec{Y}_{j,m}$$

$$\vec{A}_{j,m}^* = (-)^{m+1} \vec{A}_{j,-m}$$

$$\vec{H}_{j,m} = \frac{i\alpha_j^{TE}}{\sqrt{2j+1}} \left\{ \sqrt{j+1} j_j(\omega_j r) \vec{Y}_{j,m} - \sqrt{j} j_j(\omega_j r) \vec{Y}_{j,m} \right\}$$

$$\vec{H}_{j,m}^* = (-)^{m+1} \vec{H}_{j,-m}$$

TM

$$\vec{A}_{j,m} = \frac{\alpha_j^{TM}}{\sqrt{2j+1}} \left\{ \sqrt{j+1} j_j(\omega_j r) \vec{Y}_{j,m} - \sqrt{j} j_j(\omega_j r) \vec{Y}_{j,m} \right\}$$

$$\vec{A}_{j,m}^* = (-)^m \vec{A}_{j,-m}$$

$$\vec{H}_{j,m} = i\alpha_j^{TM} \omega_j j_j(\omega_j r) \vec{Y}_{j,m}$$

$$\vec{H}_{j,m}^* = (-)^m \vec{H}_{j,-m}$$

with the normalization

The mode numbers $J_j \equiv \omega_j a$ and modes are those given by Barnes [1], although his glucun normalizations $\{\alpha_j\}$ are large.

The mode numbers for the first few modes are

$$J_{j-1}(X) = \frac{j}{j+1} J_{j+1}(X)$$

J^P	X
1^+	2.744
2^-	3.870
	7.443

$$J_j(X) = 0$$

J^P	X
1^-	4.493
2^+	5.763
	9.905

As we shall repeatedly consider the lowest TE and TM modes, their properties are of special interest. They are explicitly

It appears in the functional integral for the expression of the generating functional $Z[J]$. In this connection the lattice regularization has frequently been used in the recent works for evaluating physical quantities of interest (see, e.g. [Cre 83]).

Dimensional regularization

The divergent multiple integral may be made convergent by reducing the number of multiple integrals. For example, the linearly divergent 4-point functions in Eq. (2.4.9) would be finite if the space-time were 2-dimensional. This fact is the basic idea of dimensional regularization [Bol 72, Ash 72, Cic 72]. In dimensional regularization we keep the space-time dimension D lower than four and replace the divergent 4-dimensional integrals by a convergent D -dimensional one. By making momentum integrations explicitly we obtain an analytic expression as a function of the dimension D . We make the analytic continuation in D in this expression. Then the final divergence will show up as a pole at $D = 4$ in the above analytic expansion. For a review, see [Lei 75].

In the dimensional regularization nothing has been violated except the space-time is not 4-dimensional, all the physical requirements are satisfied. Hence this regularized theory is Lorentz invariant, gauge invariant, and so on (Ho 72, Spe 74). In this sense dimensional regularization is the best for gauge theories. We shall give a more detailed account of this in the next subsection.

Digression

USEFUL FORMULAS FOR $SU(N)$: In the course of QCD calculations we often encounter quantities like $T^a T^a$, $f^{abc} f^{abd}$, $T^a T^b T^c$, etc, where T^a ($a = 1, 2, \dots, N^2 - 1$) are $SU(N)$ generators and f^{abc} the structure constants. We shall present here a derivation of formulas for the quantities.

The algebra of $SU(N)$ is defined by the commutation relations

$$[T^a, T^b] = i f^{abc} T^c \quad (2.4.13)$$

In the regularization condition we adopt

$$\text{Tr}(T^a T^b) = \frac{1}{2} \delta^{ab} \quad (2.4.14)$$

The trace refers to the $N \times N$ matrix in the fundamental representation. We derive the useful formula

$$T^a_i T^a_i = \frac{1}{2} (\delta_{ij} \delta_{jk} - \frac{1}{N} \delta_{ij} \delta_{kk}) \quad (2.4.15)$$

In this formula we note that the identity 1 and T^a ($a = 1, 2, \dots, N^2 - 1$) form the basis of an $(N^2) \times (N^2)$ matrix space.

$$c^a T^a = T^a \quad (2.4.16)$$

2.4. REGULARIZATION

where c^0, c^1, \dots are real numbers. The constants c^0 and c^a are determined by using the normalization condition (2.4.14):

$$c^0 = \text{Tr}(A)/N \quad (2.4.17)$$

$$c^a = 2 \text{Tr}(T^a A) \quad (2.4.18)$$

Inserting Eqs. (2.4.17-18) into Eq. (2.4.16) we have

$$A_{ik} (2T^a_{ij} T^a_{ki} + \frac{1}{N} \delta_{ij} \delta_{kk} - \delta_{ij} \delta_{kk}) = 0 \quad (2.4.19)$$

Since Eq. (2.4.19) holds for arbitrary hermitian matrix A , we obtain Eq. (2.4.15). An immediate consequence of Eq. (2.4.15) is that

$$(T^a T^a)_{ij} = \frac{N^2 - 1}{2N} \delta_{ij} \quad (2.4.20)$$

$$(T^a T^b T^a)_{ij} = -\frac{1}{2N} T^b_{ij} \quad (2.4.21)$$

We can also calculate $f^{abc} f^{abd}$ as follows. Using Eqs. (2.4.13) and (2.4.14) we have

$$f^{abc} f^{abd} = -2 \text{Tr}([T^a, T^c][T^b, T^d]) = -2 \text{Tr}(2T^a T^c T^b T^d - (T^a T^b + T^b T^a) T^c T^d) \quad (2.4.22)$$

Applying Eqs. (2.4.20) and (2.4.21) to Eq. (2.4.22), we obtain

$$f^{abc} f^{abd} = N \delta^{cd} \quad (2.4.23)$$

It should be remarked here that the $T^a T^a$ appearing in Eq. (2.4.20) is the Casimir operator of the group $SU(N)$ and hence commutes with all the operators in $SU(N)$. By Schur's lemma such an operator is a multiple of the identity operator. In general the number of independent Casimir operators is equal to the rank of the group.

2.4.2. Dimensional regularization

We carry on our discussion by using our example of the one-loop quark self-energy part in the Feynman gauge (2.4.9). We now move off from 4-dimensional space-time to D dimensions by replacing the 4-dimensional integral d^4k by the D -dimensional one d^Dk . In performing the D -dimensional integration, we mention that some care has to be given to the algebra in D dimensions.

First of all the space-time index μ now runs from 0 to $D-1$ so that components of a momentum vector are

$$p^\mu = (p^0, p^1, \dots, p^{D-1}) \quad (2.4.24)$$

and the contracted metric tensor is

$$g^\mu_\nu = \delta_{\mu\nu} g^{\mu\nu} = D$$

The Dirac algebra in D dimensions is unchanged except that the gamma matrices are γ^μ instead of γ^i . The Dirac equation is $(\not{p} - m)\psi = 0$.