## A Topology Viewer For Distributed Brokering Systems

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# **Talk Outline**

- Introduction
- Related Work
- Our approach
- Results
- Conclusions and Future Work

### Introduction

- Network ⇔Graph Visualization
- Challenges
  - Scalability Displaying large number of nodes and links on screen without losing context.
  - Navigation and Efficiency Traversing through the networked graph and fetch the information associated with the components.
  - Adaptability Reconstruction of the graph depending upon dynamic change in the components.
- Typical Graph Hierarchical in nature
  - Clustering technique helps maintain abstraction

#### **Related Work – I**





- Treemaps Space Filling method.
  - Nodes are represented by rectangles. Rectangles are packed in 2D plane.
  - 100% utilization of the space.
  - Not scalable.
- Cone Trees
  - Rooted tree layout
  - Children are placed on the circumference around the cone.
  - Limitation on size of the graph.

#### **Related Work – II**





- 3D Layout
  - Use of Hyperbolic geometry
  - Rendering is time consuming
- RINGS
  - Children placed as equal size circles in the concentric rings around center of the parent circle.
  - Minimum edge crossings.
- Easy navigation Clicking on the node makes it the focus while overall context is maintained.

#### NaradaBrokering Overview

- Open source project. <u>http://www.naradabrokering.org</u>
- Provides a variety of services
  - Reliable, ordered and exactly once delivery.
  - Compression and fragmentation of large payloads.
  - Performance Monitoring service
  - Support for multiple subscription types
- Used in the context of A/V applications and to enhanced Grid apps such as Grid-FTP
- Provides support for variety of transports: TCP, UDP, HTTP, SSL, Multicast and parallel TCP streams.
- JMS compliant. Will provide WS-Notification support.
- Includes bridge to GT3. April 2004 release.
- Support for Web Services being incorporated.

#### NaradaBrokering: Topology Viewer Goals

- NaradaBrokering
  - Runs on large number of co-operating broker nodes.
  - Broker Node is smallest unit and is used to route messages encapsulating any sort of information.
  - Inherent hierarchical nature. Four levels of clusters and so four levels of abstractions.
- Goals of the Topology Viewer
  - Should be quite scalable (Max Nodes = 32 \* 32 \* 32 \* 32)
  - Algorithmic and Navigational efficiency.
  - Incorporate dynamic changes in the network with minimum variation in the layout.

# Layout Algorithm

- Node Placement
  - Graph placed inside a BIG circle. Highly Symmetric.
  - Each level (Super Super Cluster, Super Cluster, Cluster and Broker Node) is represented by a circle and components in a same level are placed inside the parent circle.
  - As opposed to RING scheme, children are placed in a single ring instead of multiple concentric rings
    - Improves calculation and navigational efficiency BUT poor space utilization
  - If n children inside parent and then angular separation is  $2\pi$  / n.

# **Layout Algorithm – Continued**

- Radius of a circle can be easily calculated. If angular separation is Θ then the radius would be R Sin(Θ/2). R is the radius of parent circle.
- Decision whether a component lie on the screen is simple. Due to abstraction, the decision can be made with few comparisons.
- Based on the mouse coordinates, unique node can be located with few comparisons.
- Edge Placement
  - Straight edges reduce drawing and calculation overhead. Minimizing edge crossings.
  - Edges between nodes at diff levels in diff colors.

## **Sample View – Explanation**



- Entire Diagram lies inside in BIG virtual circle.
- Outermost circles represent super-super clusters, then superclusters and so on.
- Cluster/ Node Ids are shown at the top.
- Edges are straight and have different colors.

# **Navigation – Translation**



- Difference between the old center of the graph and the new focus is calculated.
- All the centers of components are recalculated.
- Circle Best choice as it can described by only two parameters (x, y)
- Whole graph is shifted so that new focus becomes center of the screen.

# Navigation – Zoom In/ Out



- Two figures correspond to views before and after zooming.
- Radius of each circle is increased by fixed constant.
- Center of the outermost virtual circle is recalculated.
- Whole picture is redrawn on the screen.

#### **Performance – Drawing Response**



The system has been tested up to 10000 nodes.Restricted view (Few

components), display time reduces (due algorithmic and visual simplicity)

Degree of independence on the number of nodes in system is high. Hence Scalable.

#### **Performance - Zoom Operations**



- Adjacent graph shows time required to perform all recalculations and excludes the display time.
- As expected the response time increases linearly with number of nodes.
- Time is in tens of milliseconds is small fraction of actual display time. So does not involve significant overhead compared to display time

### **Performance - Node Operations**



- Complexity for determining a node address from (x, y) coordinates is also O (N). Because of symmetry in the system such decision can be made in at most 4 \* N comparisons.
- Independent on number
  of nodes in the system.
  Stabilizes after some node additions.

### **Conclusion and Future Work**

- Very scalable and clear.
- Incorporate dynamic changes in the network.
- Algorithmic and visual simplicity.
- What Next !
  - Provide mechanism so that one can access to monitoring service associated with each node. Viewer acts as information fetching tool.
  - Allow user run their own instances of the viewer and synchronize them with the viewer running at main site

### **Percentage Space Wasted**

- Assume that Radius of the virtual circle is R
- If number of children (Super-super clusters) are N
- Total Available space is ΠR<sup>2</sup>
- Space used is N \*  $\Pi$  \* R<sup>2</sup> sin <sup>2</sup> ( $\Pi$ /N)
- Percentage space wasted is  $(1 N \sin^2 (\Pi/N))$  %
- As N increases, value of sin<sup>2</sup> (Π/N) decreases drastically and so more space is wasted.