

Fig. 1 Bodies in contact with each other

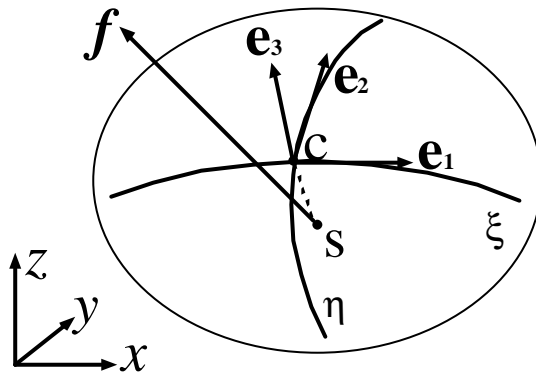
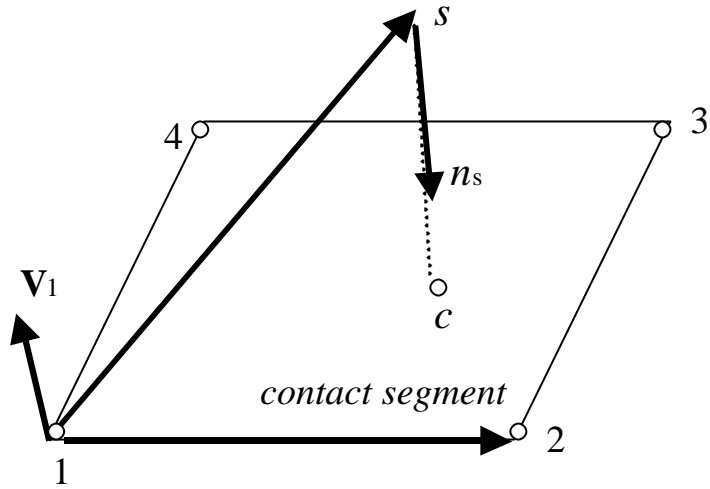


Fig.2 Frame for calculation of the contact force



$$V_i = \vec{ik} \times \vec{is} \quad (i = 1, 4)$$

$$k = i + 1 \text{ if } i = 1, 3, \text{ otherwise } k = 1$$

Fig. 3 Local contact search algorithm

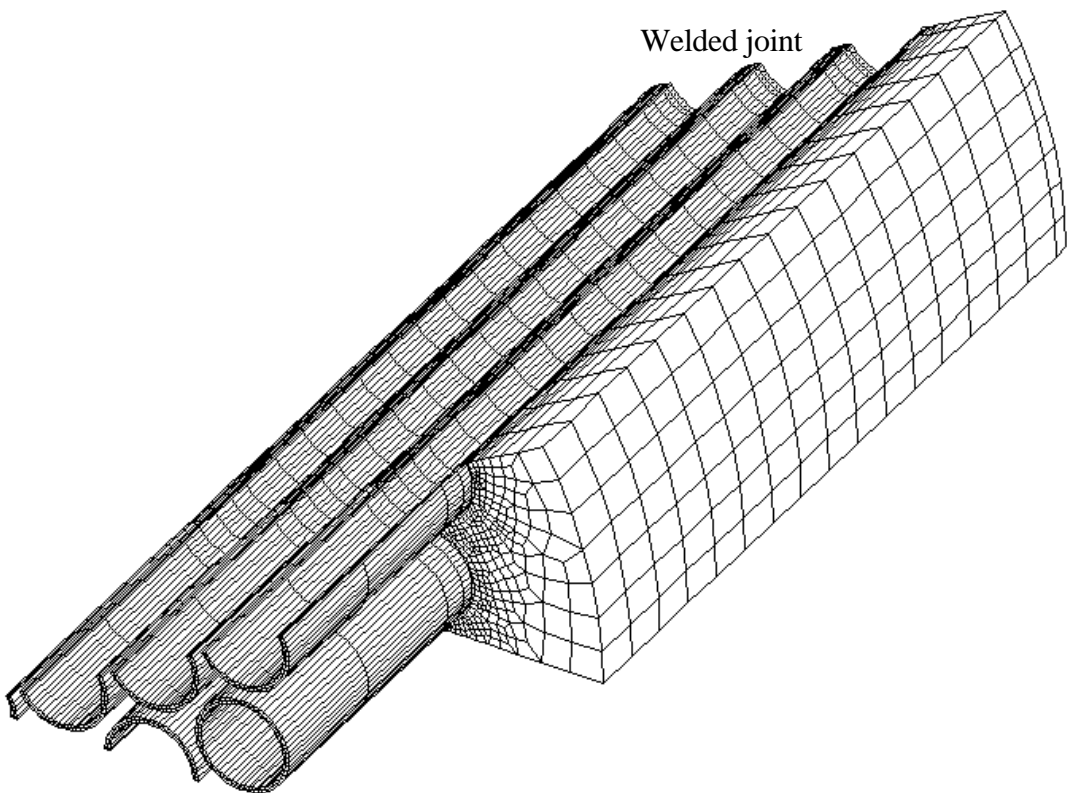


Fig. 4 The geometry and mesh of tube and tubesheet structure analyzed

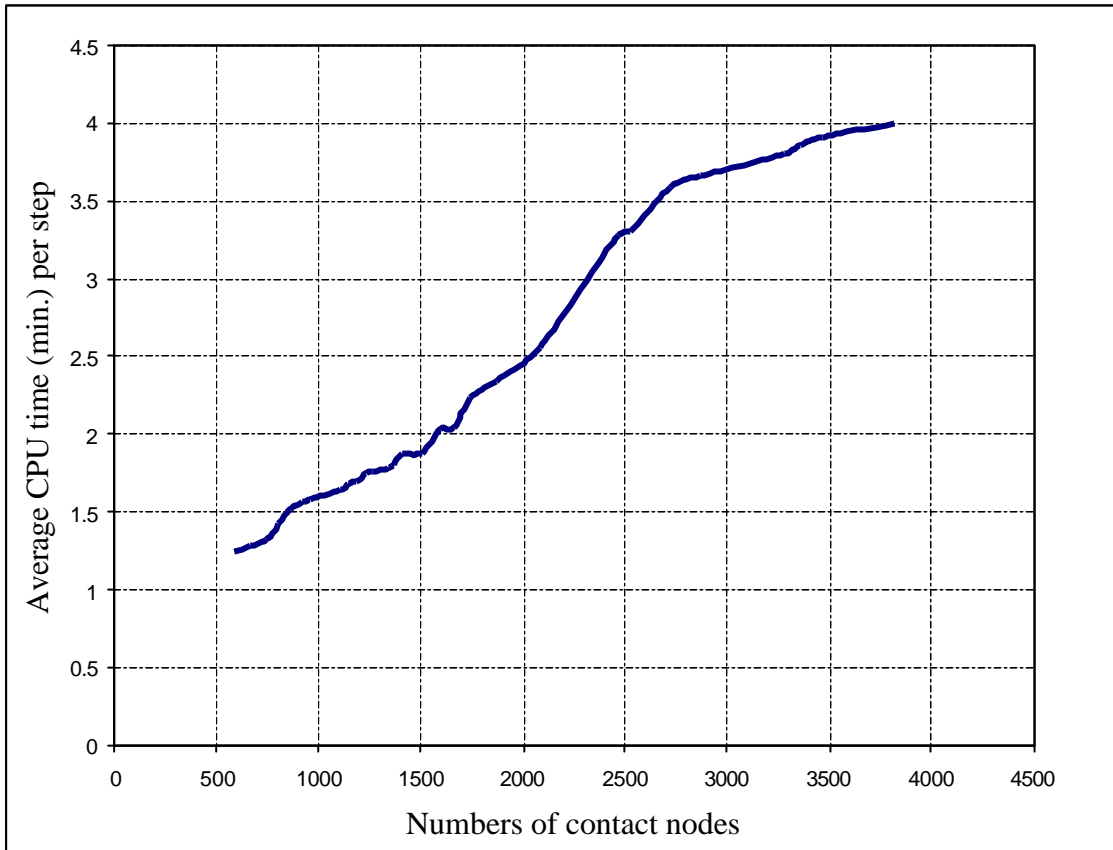
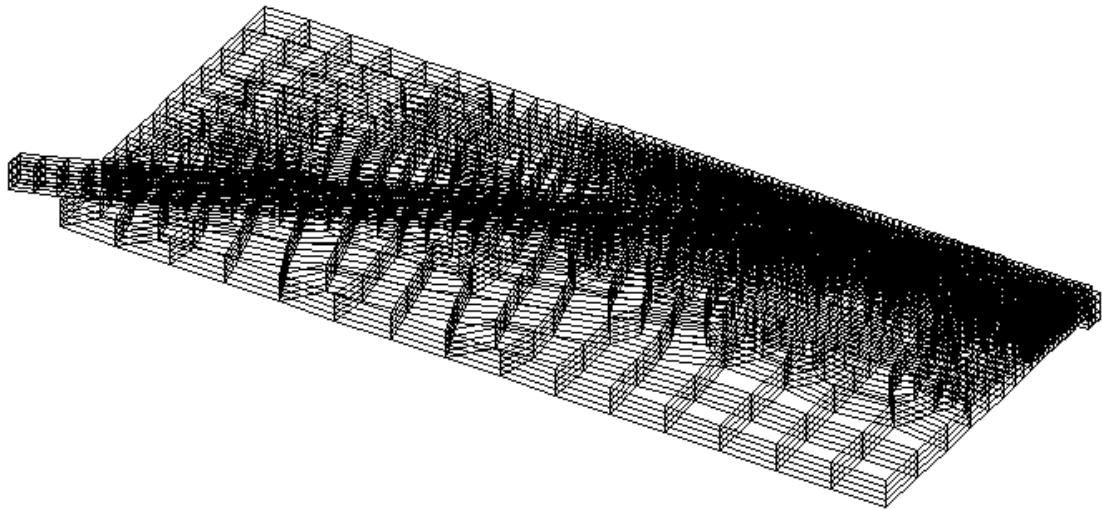
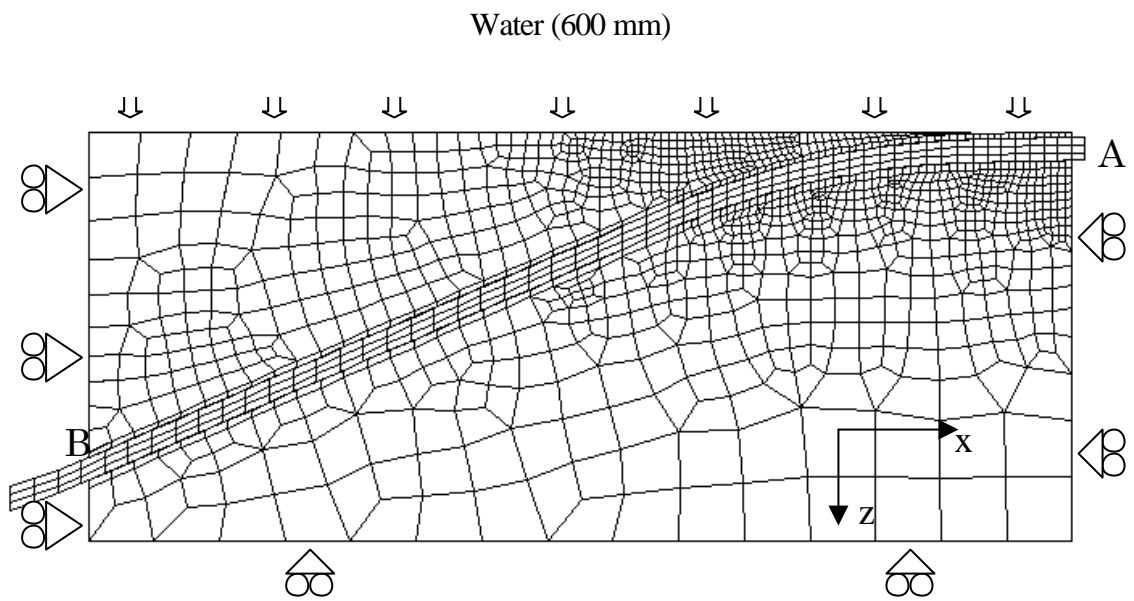


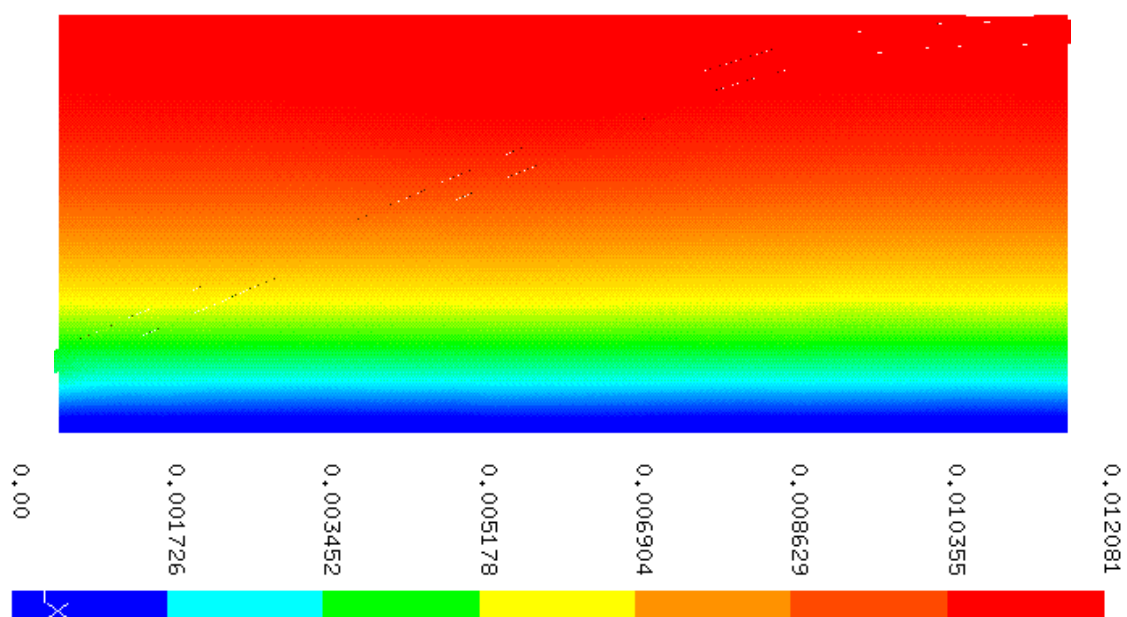
Fig. 5 Average CPU time vs. numbers of contact nodes



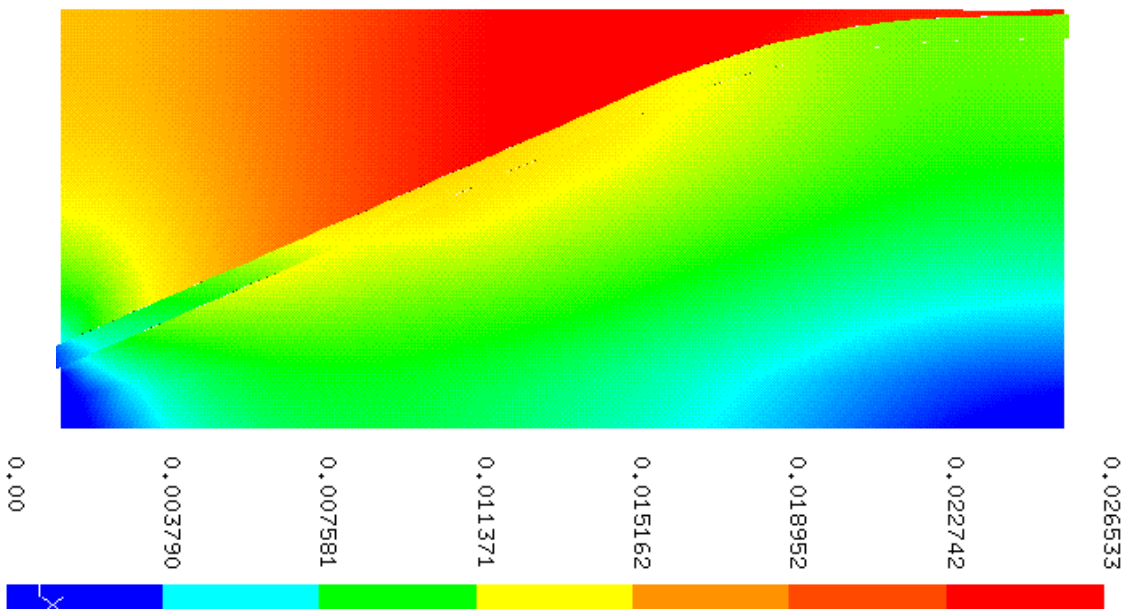
Dimensions: 20038 x 51 x 600 mm^3

Loading condition: gravity force + hydraulic pressure

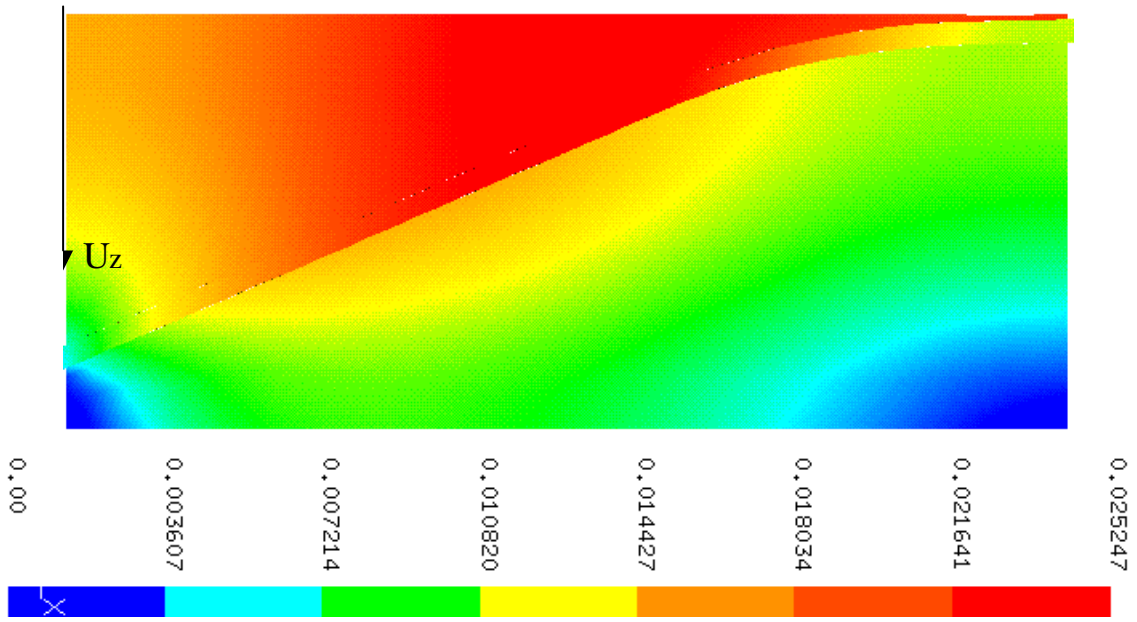
Fig. 6 The Northeast fault model with the Pacific plate analyzed



(a)



(b)



(c)

Fig. 7 Displacement distribution at different friction conditions:

(a). $\mathbf{m} = 0.5$; (b). $\mathbf{m} = 0.3$;

(c). $\mathbf{m} = 0.3 (U_z \leq 150 \text{ or } U_z \geq 278)$, otherwise $\mathbf{m} = 0.5 - 0.025 \ln(\tilde{u}_{eq}^{sl}/0.01)$