

Fig. 1 Bodies in contact with each other

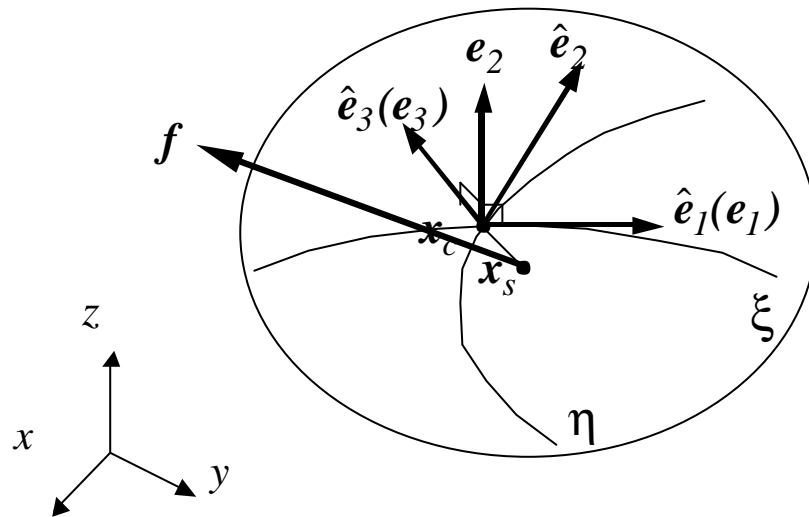
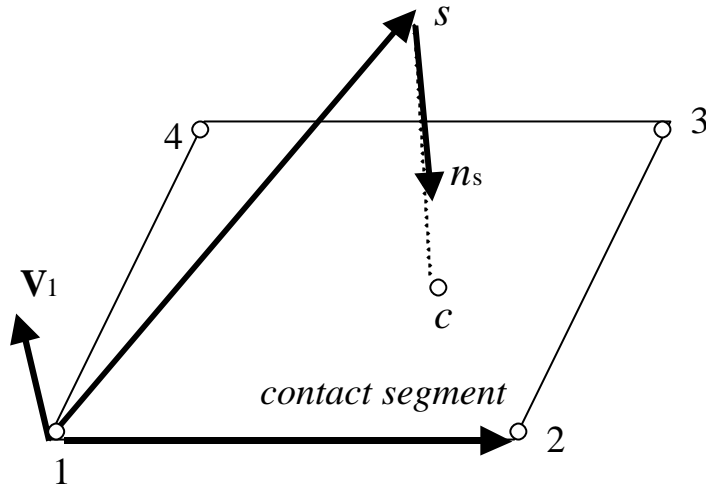


Fig.2 Frame for calculation of the contact stress



$$V_i = \vec{ik} \times \vec{is} \quad (i = 1, 4)$$

$$k = i + 1 \text{ if } i = 1, 3, \text{ otherwise } k = 1$$

Fig. 3 Local contact search algorithm

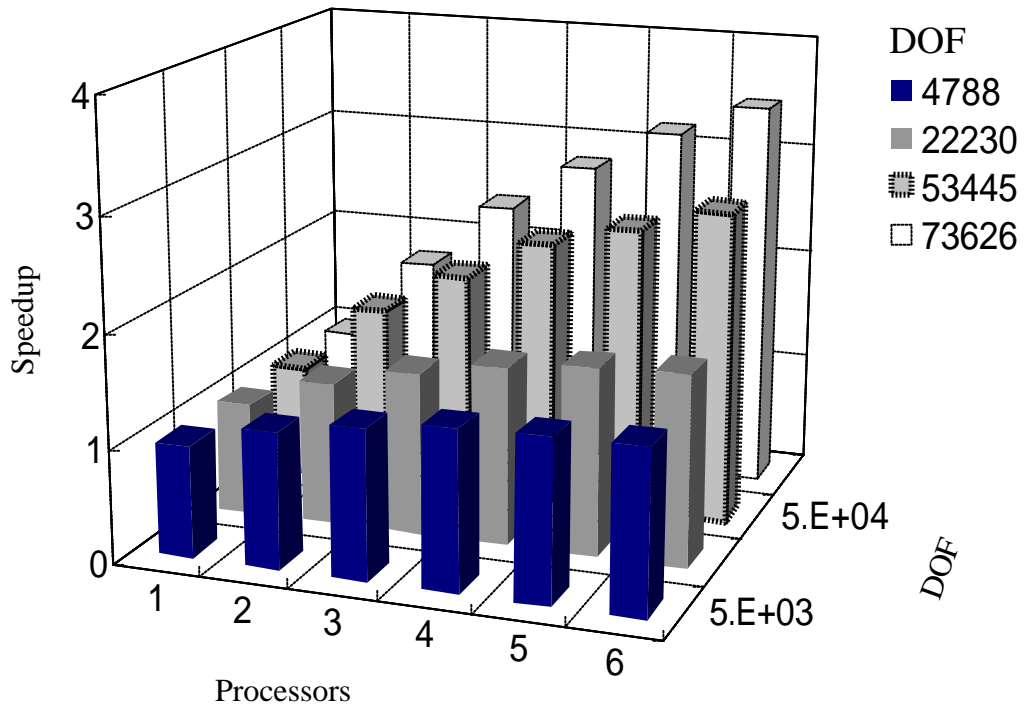


Fig.4 Speedup for different cases

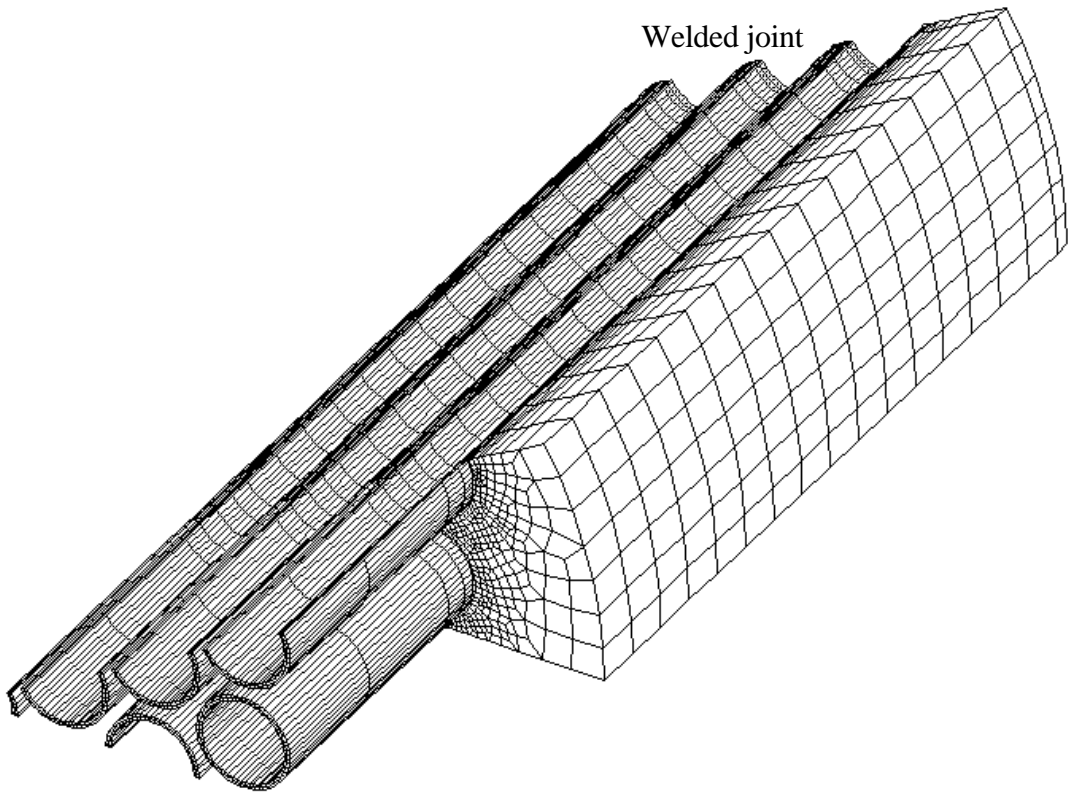


Fig. 5 The geometry and mesh of tube and tubesheet structure analyzed

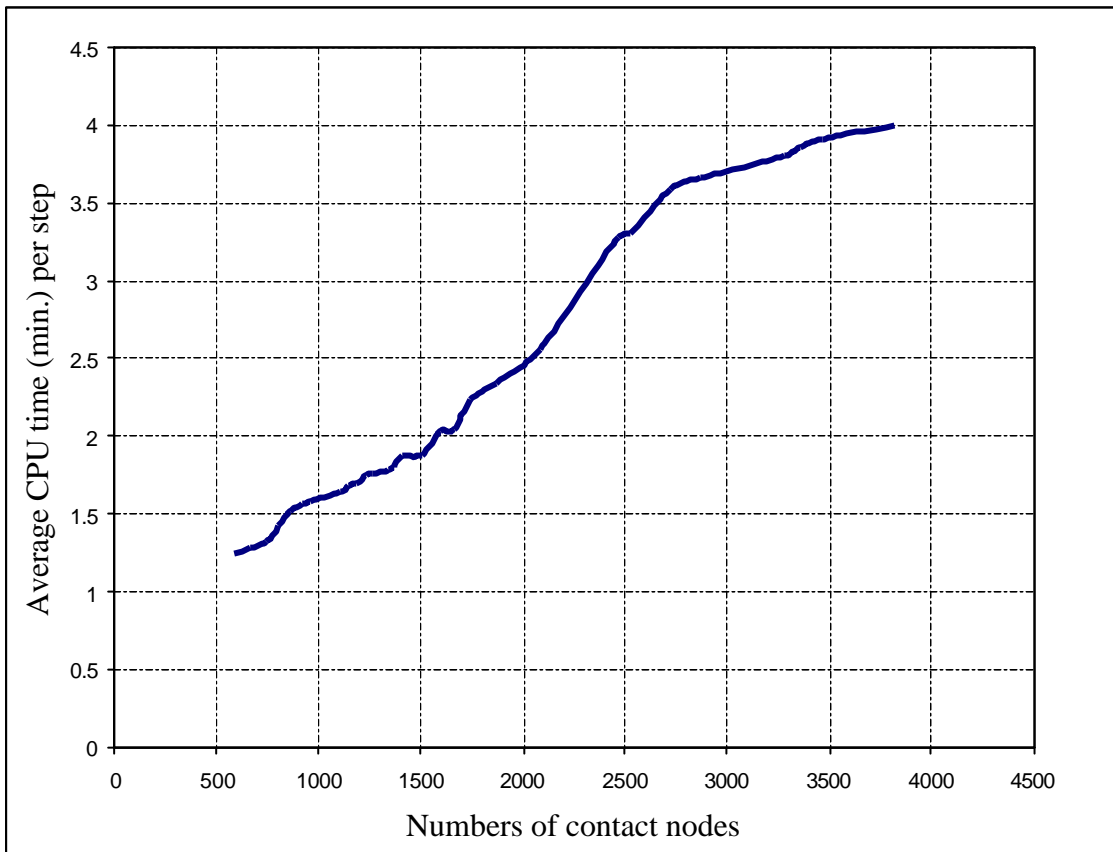


Fig. 6 Average CPU time vs. numbers of contact nodes

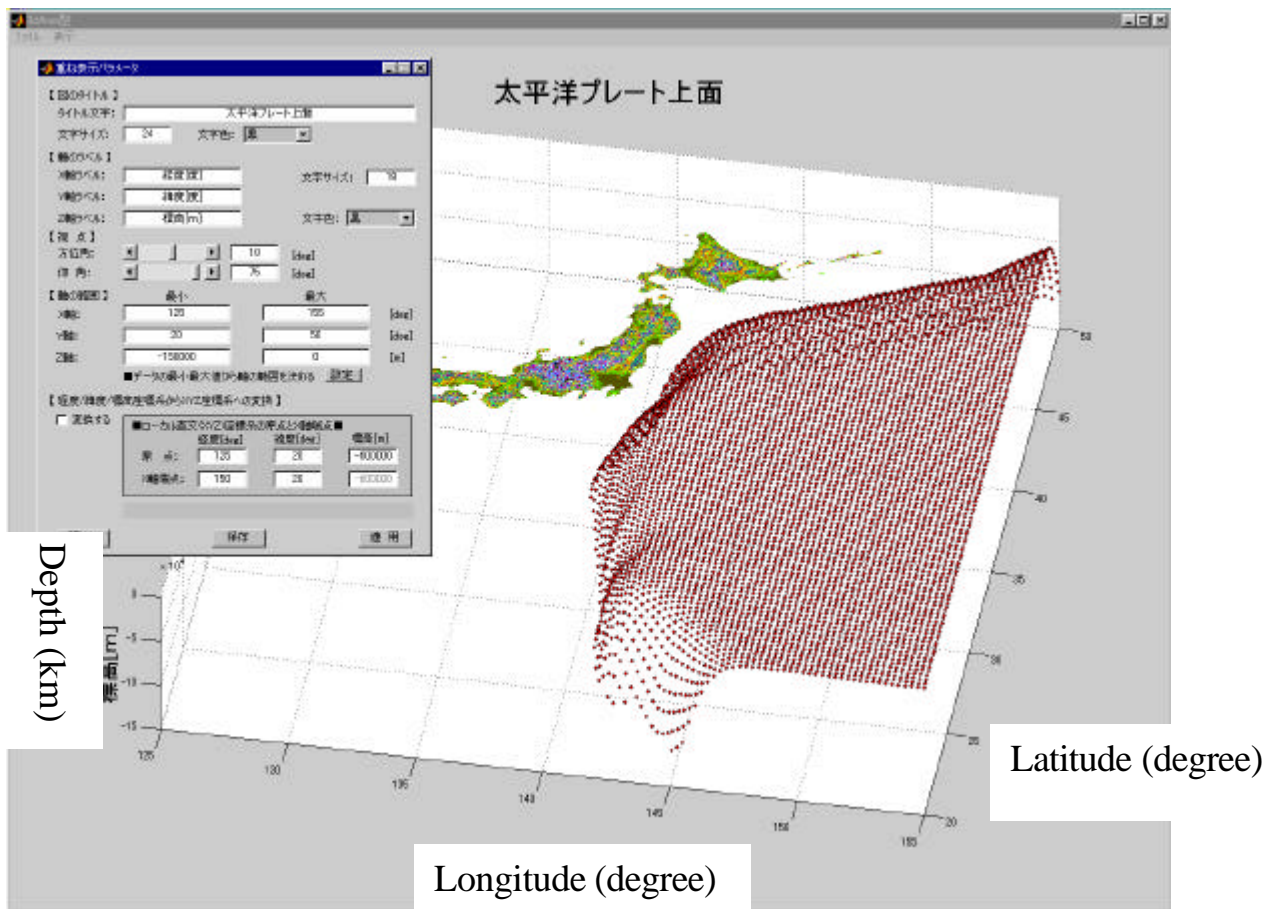


Fig. 7 The upper surface of the Pacific plate around Japan (Kanai, 2000)

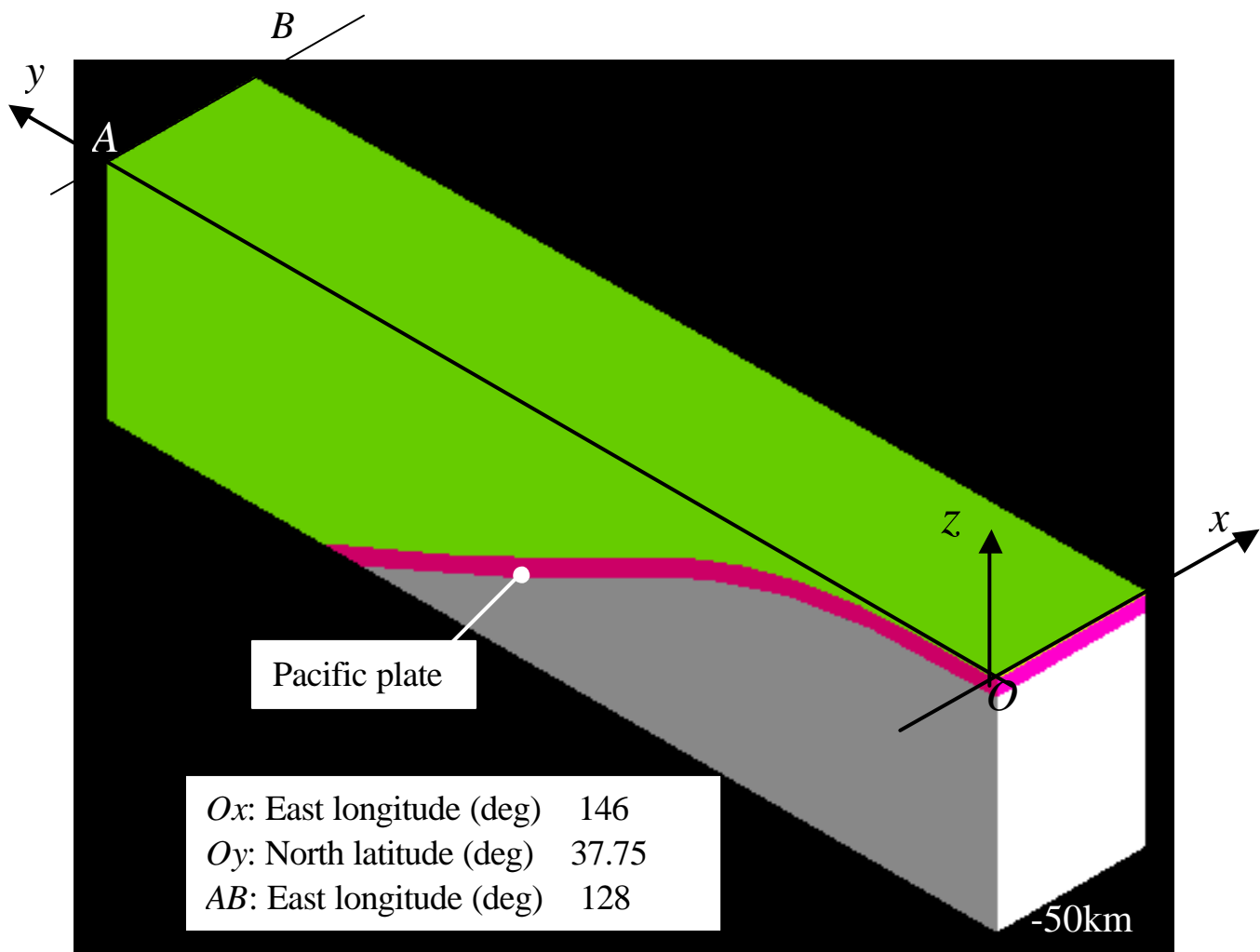
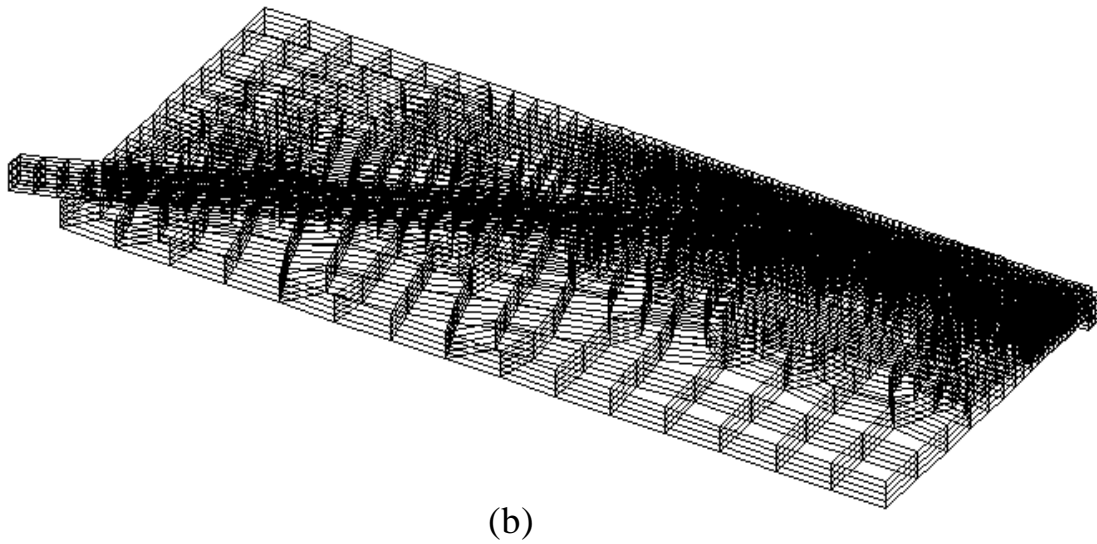
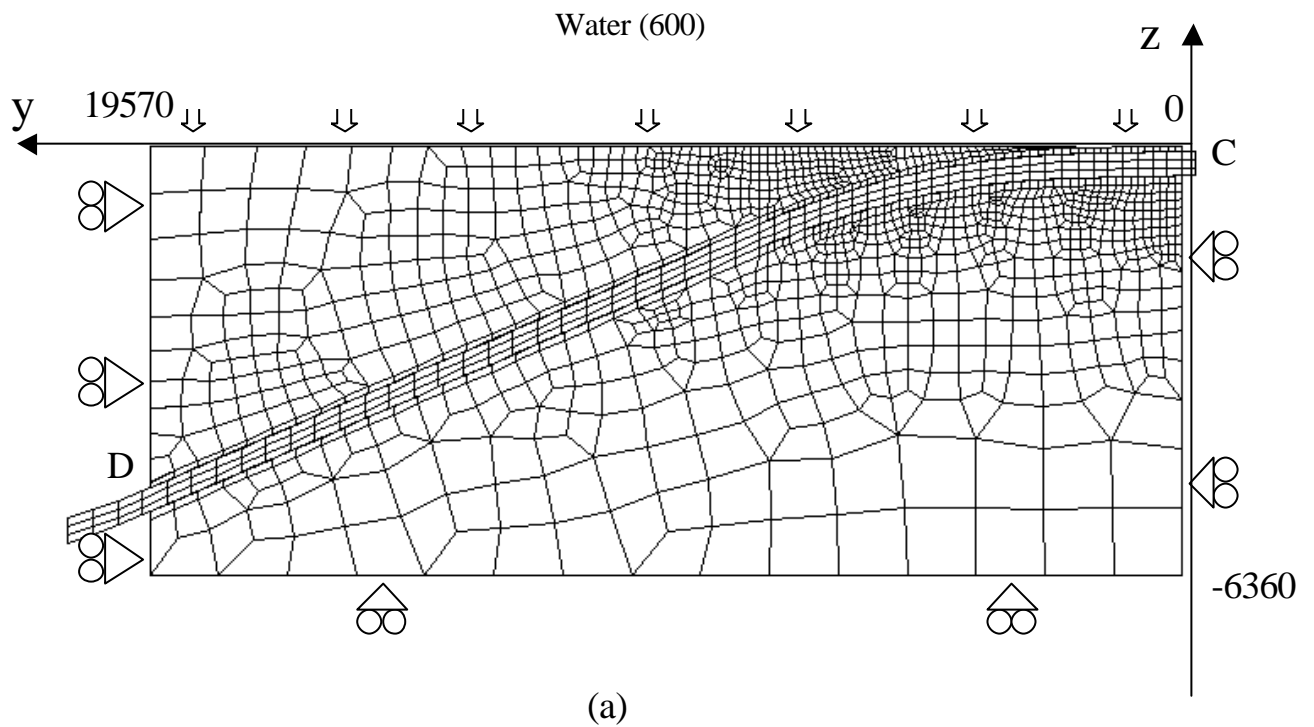


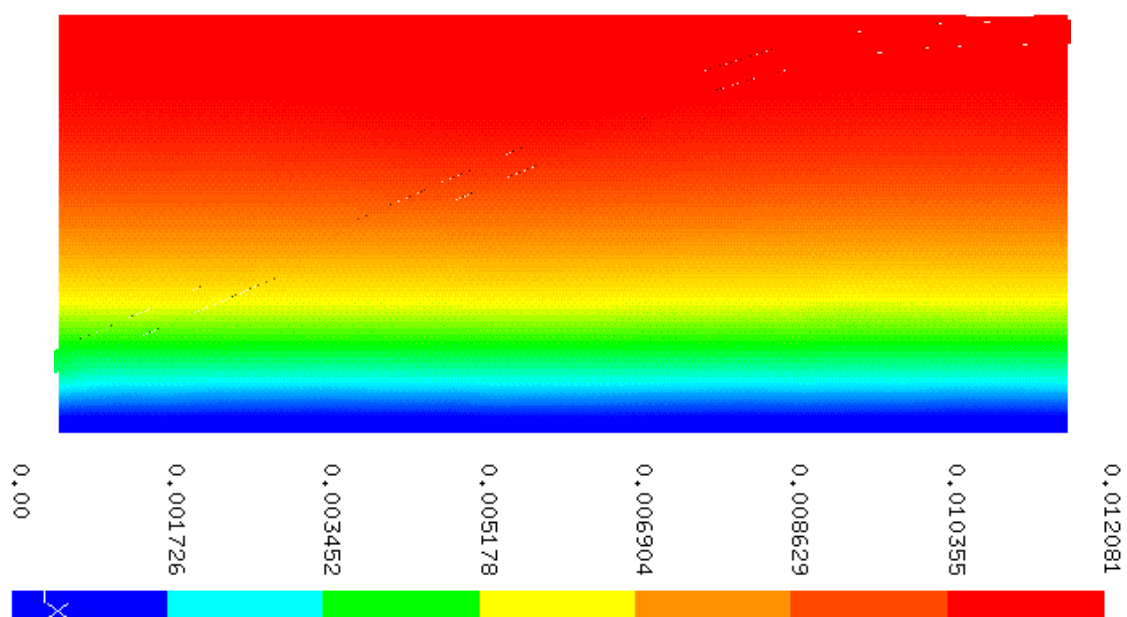
Fig. 8 A part of the tectonic solid model of the Northeast zone of Japan (Kanai, 2000)



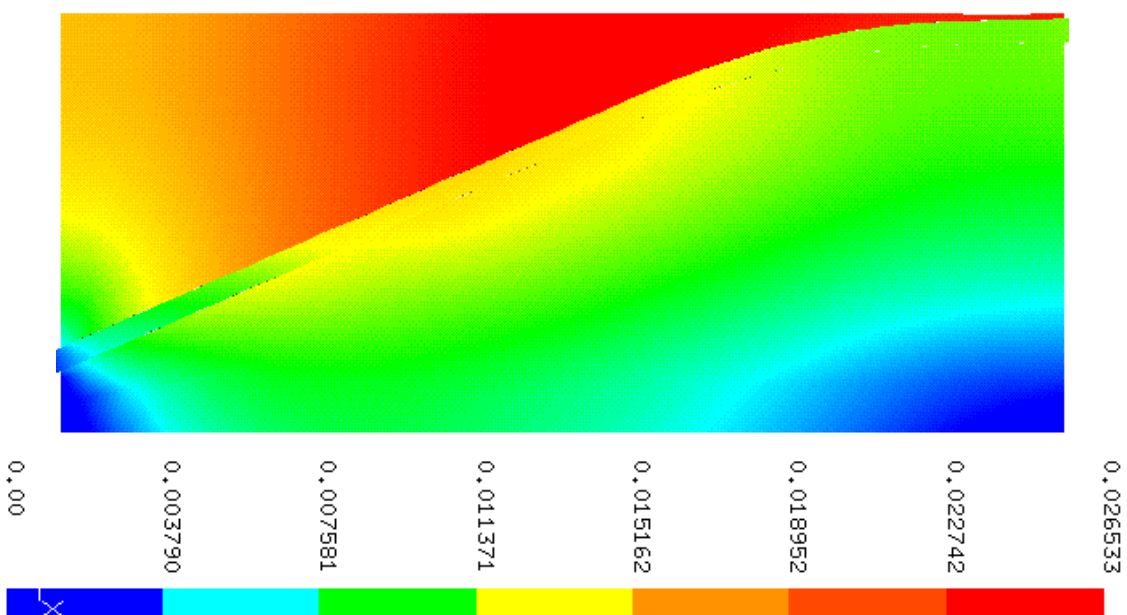
Dimensions: 19570 x 510 x 6360 mm^3

Loading condition: gravity force + hydraulic pressure

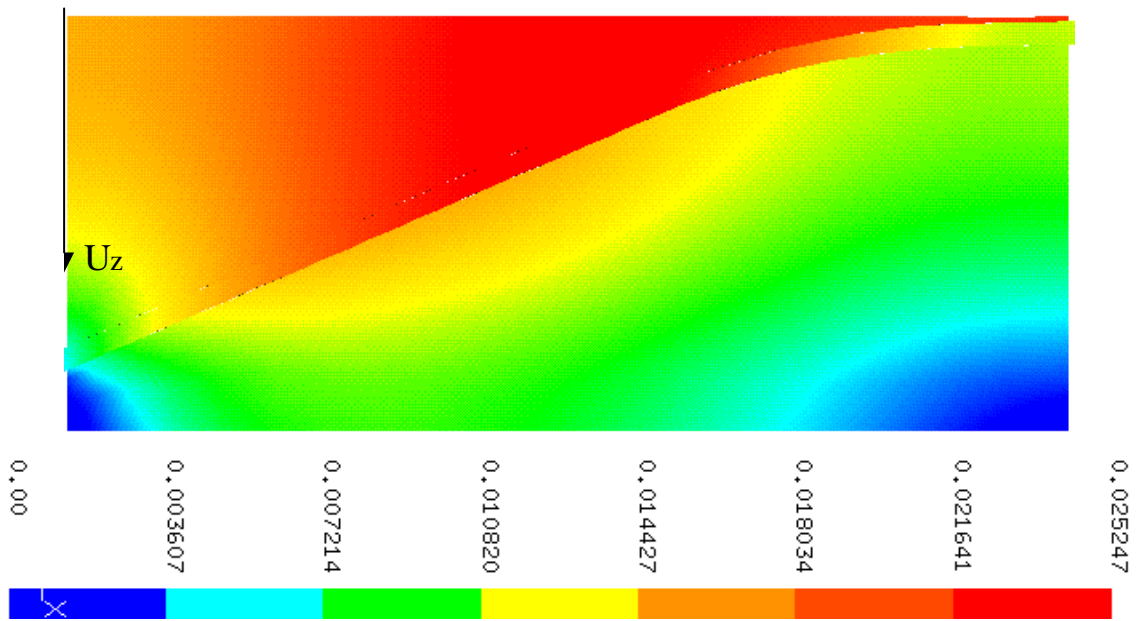
Fig. 9 The mesh used for the Northeast fault model with the Pacific plate in (a) the y-z cross section (along OA in Fig. 8) and (b) the three dimensions



(a)



(b)



(c)

Fig. 10 Displacement distribution at different friction conditions:

(a). $\mathbf{m} = 0.5$; (b). $\mathbf{m} = 0.3$;

(c). $\mathbf{m} = 0.3 (U_z \leq 1500 \text{ or } U_z \geq 2780)$, otherwise $\mathbf{m} = 0.5 - 0.025 \ln(\tilde{u}_{eq}^{sl}/0.01)$